## Statistical functionals and influence functions

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In our first lecture, we introduced the empirical distribution function as a nonparametric way of estimating F, and showed that it had a number of very attractive properties:

- $\hat{F} \xrightarrow{\text{a.s.}} F$ , regardless of F
- The nonparametric maximum likelihood estimator
- Able to derive confidence intervals and confidence bands that work for any F, any n, and all x

#### Parametric vs. nonparametric estimation

- Why so much emphasis on estimating F?
- Because  $\hat{F}$  will play the same role in nonparametric estimation that  $\hat{\theta}$  played in parametric estimation
- In parametric statistics, we find the most likely distribution of the data based on  $\hat{F}=F(\hat{\theta})$
- This then provides estimates of our parameters of interest usually  $\theta$  itself or some function of  $\theta$ , such as  $e^{\theta}$ , but conceivably also something like the 75th percentile

## Nonparametric estimation

- Clearly, nonparametric statistics does not provide estimates of parameters (or functions of parameters) ... so what are we estimating in nonparametric statistics?
- We estimate what are called *statistical functionals*: a functional  $\theta = T(F)$  is any function of F
- Many common descriptive statistics can be expressed as statistical functionals

## Examples

- Mean:  $T(F) = \int x \, dF(x)$
- Variance:  $T(F) = \int (x \mu)^2 dF(x)$
- Quantiles:  $T(F) = F^{-1}(p)$

#### Estimation of statistical functionals

• Estimation of these quantities is straightforward: calculate the quantity you are interested in based on the nonparametric maximum likelihood estimator of F, the empirical distribution function  $\hat{F}$ :

$$\hat{\theta} = T(\hat{F})$$

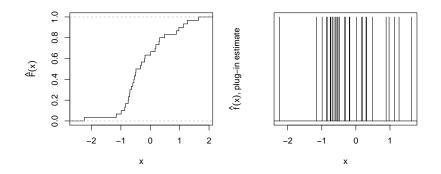
- This idea is often called the *plug-in principle*, and its resulting estimate the *plug-in estimate*
- Examples:
  - Mean:  $\bar{x}$
  - Variance:  $n^{-1}\sum (x_i \bar{x})^2$
  - Quantile: Sample quantile
- In a sense, the plug-in principle is a nonparametric analog of the likelihood principle

#### Is the plug-in estimator a good estimator?

- A natural question: Is the plug-in estimator a good estimator?
- The Glivenko-Cantelli Theorem says that  $\hat{F} \xrightarrow{a.s.} F$ ; does this mean that  $T(\hat{F}) \xrightarrow{a.s.} T(F)$ ?
- The answer turns out to be a complicated "sometimes"; often "yes", but not always

#### Plug-in density estimation

As an example of a case where the plug-in estimator is not consistent, consider density estimation, where T(F) = F'(x):



# The influence function

- So when is the plug-in estimator consistent?
- It requires certain conditions on the smoothness (differentiability) of T(F)
- But what does it mean to take the derivative of a function with respect to a function?
- To answer this question, we will have to expand our notion of the derivative

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#### The Gâteaux derivative

- The extension of the derivative that we will need is called the *Gâteaux derivative*
- The Gâteaux derivative of T at  ${\cal F}$  in the direction  ${\cal G}$  is defined by

$$L_F(T;G) = \lim_{\epsilon \to 0} \left[ \frac{T\{(1-\epsilon)F + \epsilon G\} - T(F)}{\epsilon} \right]$$

• An equivalent way of stating the definition is to define D = G - F, and the above becomes

$$L_F(T;D) = \lim_{\epsilon \to 0} \left[ \frac{T\{F + \epsilon D\} - T(F)}{\epsilon} \right]$$

• Either way, the definition boils down to

$$L_F(T) = \lim_{\epsilon \to 0} \left[ \frac{T(F_{\epsilon}) - T(F)}{\epsilon} \right]$$

#### Interpretation

- From a mathematical perspective, the Gâteaux derivative a generalization of the concept of a directional derivative to functional analysis
- From a statistical perspective, it represents the rate of change in a statistical functional upon a small amount of contamination by another distribution G

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## Gâteaux derivative of f(x)

- As an example of how the Gâteaux derivative works, suppose F is a continuous CDF, and G is the distribution that places all of its mass at the point  $x_0$
- What happens to the Gâteaux derivative of  $T(F) = f(x_0)$ ?

$$L_F(T;G) = \lim_{\epsilon \to 0} \left[ \frac{\frac{d}{dx} \{(1-\epsilon)F(x) + \epsilon G(x)\}_{x=x_0} - \frac{d}{dx}F(x)|_{x=x_0}}{\epsilon} \right]$$
$$= \lim_{\epsilon \to 0} \left[ \frac{(1-\epsilon)f(x_0) + \epsilon g(x_0) - f(x)}{\epsilon} \right]$$
$$= \infty$$

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#### Glivenko-Cantelli does not imply convergence of estimators

- So, even though F and  $F_\epsilon$  differ from each other only infinitesimally T(F) and  $T(F_\epsilon)$  differ from each other by an infinite amount
- Thus, the Glivenko-Cantelli theorem does not help us here:  $\sup_x \left| \hat{F}(x) F(x) \right|$  may go to zero without  $T(\hat{F}) \to T(F)$

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## Hadamard differentiability

- $\bullet\,$  It turns out that even Gâteaux differentiability is too weak to ensure that  $T(\hat{F}) \to T(F)$
- Even if the Gâteaux derivative exists, it may not exist in an entirely unique way, and this is the subtle idea introduced by *Hadamard differentiability*
- A functional T is Hadamard differentiable if, for any sequence  $\epsilon_n \to 0$  and  $D_n$  satisfying  $\sup_x |D_n(x) D(x)| \to 0$ , we have

$$\frac{T(F + \epsilon_n D_n) - T(F)}{\epsilon_n} \to L_F(T; D)$$

• If T is Hadamard differentiable, then  $T(\hat{F}) \xrightarrow{\mathsf{P}} T(F)$ 

#### Bounded functionals

Another useful condition that — certainly, one that is easier to check than Hadamard differentiability — is that if the functional is bounded, then the plug-in estimate will converge to the true value

**Homework:** Suppose that there exists a constant C such that the following relation holds for all G:

$$|T(F) - T(G)| \le C \sup_{x} |F(x) - G(x)|.$$

Show that  $T(\hat{F}) \xrightarrow{\text{a.s.}} T(F)$ .

## Contamination by a point mass

- The idea of contaminating a distribution with a small amount of additional data has a long history in statistics and the investigation of robust estimators
- Statisticians usually do not work with the general Gâteaux derivative, but a special case of it called the *influence function*, in which G places a point mass of 1 at x:

$$\delta_x(u) = \begin{cases} 0 & \text{if } u < x \\ 1 & \text{if } u \ge x \end{cases}$$

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#### The influence function and empirical influence function

• The influence function is usually written as a function of x, and defined as

$$L(x) = \lim_{\epsilon \to 0} \left[ \frac{T\{(1-\epsilon)F + \epsilon \delta_x\} - T(F)}{\epsilon} \right]$$

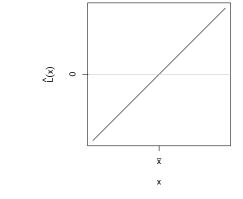
• A closely related concept is that of the *empirical influence function*:

$$\hat{L}(x) = \lim_{\epsilon \to 0} \left[ \frac{T\{(1-\epsilon)\hat{F} + \epsilon\delta_x\} - T(\hat{F})}{\epsilon} \right]$$

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#### Example: The mean

$$\begin{split} L(x) &= x - \mu \\ \hat{L}(x) &= x - \bar{x} \end{split}$$



## Linear functionals

• The mean is an example of a *linear functional*: one in which

$$T(F) = \int a(x)dF(x)$$

• Linear functionals are particularly easy to work with, as

$$L(x) = a(x) - T(F)$$
$$\hat{L}(x) = a(x) - T(\hat{F})$$

#### The chain rule

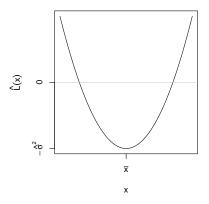
- Working directly from the definition each time is time-consuming
- Fortunately, the Gâteaux derivative has many of the same properties as ordinary derivatives in particular, the chain rule
- Suppose our functional can be written in the form  $T(F) = a\{T_1(F), T_2(F), \ldots\}$ ; then

$$L(x) = \sum_{j} \frac{\partial a}{\partial T_{j}} \bigg|_{F} L_{j}(x),$$

where  $L_j(x)$  is the influence function of  $T_j(F)$ 

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#### Example: Variance



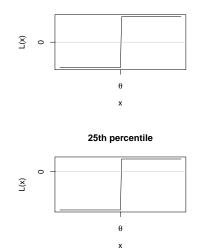
$$L(x) = (x - \mu)^2 - \sigma^2$$
$$\hat{L}(x) = (x - \bar{x})^2 - \hat{\sigma}^2$$

**Homework:** Consider a random variable X that is always positive. We are interested in the statistical functionals  $\theta = \int \log(x) dF(x)$  and  $\lambda = \log(\mu)$ .

- (b) What are the influence and empirical influence functions for  $\theta$ ?
- (d) What are the influence and empirical influence functions for  $\lambda$ ?
- (f) Do  $\hat{\lambda}$  and  $\hat{\theta}$  converge to the same number?
- (g) Plot the empirical influence functions from parts (b) and (d). Label the point x on the horizontal axis where L(x) = 0.
- (h) Briefly, comment on the relative robustness of  $\hat{\theta}$  and  $\hat{\lambda}$  to outliers.

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## Example: Quantiles



Median

$$L(x) = \begin{cases} \frac{p-1}{f(\theta)} & \text{if } x \le \theta\\ \frac{p}{f(\theta)} & \text{if } x > \theta \end{cases}$$
$$\hat{L}(x) = ?$$

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## Homework

#### **Homework:** Show that, for $x > \theta$ ,

$$L(x) = \frac{p}{f(\theta)}$$

## Breakdown point

- Note that the influence function for the median is unbounded, while the influence function for the mean is not
- Homework: Let  $b(\epsilon) = \sup_x |T(F) T(F_{\epsilon})|$ , where  $F_{\epsilon} = (1 \epsilon)F + \epsilon \delta_x$ . The breakdown point of an estimator,  $\epsilon^*$ , is defined as  $\epsilon^* = \inf\{\epsilon : b(\epsilon) = \infty\}$ 
  - a) Find the breakdown point of the mean
  - b) Find the breakdown point of the median