

# Travelling Wave Solutions of the Codazzi-Betchov-Da Rios Evolution Equations 

## Álvaro Pámpano Llarena

School of Low Dimensional Topology

Zaragoza, January 18-27 of 2017

Index

## Index

1. Generalized Kirchhoff Centerlines

## Index

1. Generalized Kirchhoff Centerlines
2. Binormal Evolution Surfaces

## Index

1. Generalized Kirchhoff Centerlines
2. Binormal Evolution Surfaces
3. Travelling Wave Solutions

## Generalized Kirchhoff Centerlines

1. Energy Functionals

## Generalized Kirchhoff Centerlines

1. Energy Functionals
2. Reduction Theorem

## Generalized Kirchhoff Centerlines

1. Energy Functionals
2. Reduction Theorem
3. Euler-Lagrange Equations

## Generalized Kirchhoff Centerlines

1. Energy Functionals
2. Reduction Theorem
3. Euler-Lagrange Equations
4. Killing Vector Fields

## Energy Functionals

- We denote by $\Omega_{p_{o} p_{1}}$ the space of smooth immersed curves of $M_{r}^{n}(\rho)$ joining two points of it.


## Energy Functionals

- We denote by $\Omega_{p_{o} p_{1}}$ the space of smooth immersed curves of $M_{r}^{n}(\rho)$ joining two points of it.
- We are going to consider energy functionals acting on $\Omega_{p_{o} p_{1}}$ of the following form

$$
\Theta(\gamma)=\int_{\gamma} \mathcal{F}(\kappa)+\mu \tau+\lambda=\int_{0}^{L}(\mathcal{F}(\kappa)(s)+\mu \tau(s)+\lambda) d s
$$

where $\mathcal{F}(u)$ is a $C^{\infty}(\mathbb{R})$ function and $\mu, \lambda \in \mathbb{R}$.

## Energy Functionals

- We denote by $\Omega_{p_{0} p_{1}}$ the space of smooth immersed curves of $M_{r}^{n}(\rho)$ joining two points of it.
- We are going to consider energy functionals acting on $\Omega_{p_{o} p_{1}}$ of the following form

$$
\Theta(\gamma)=\int_{\gamma} \mathcal{F}(\kappa)+\mu \tau+\lambda=\int_{0}^{L}(\mathcal{F}(\kappa)(s)+\mu \tau(s)+\lambda) d s
$$

where $\mathcal{F}(u)$ is a $C^{\infty}(\mathbb{R})$ function and $\mu, \lambda \in \mathbb{R}$.

- A version of the Lagrange multipliers allows us to interpret this variational problem as the minimization of the curvature energy $\int_{\gamma} \mathcal{F}(\kappa)$ subject to two constraints: fixed length and fixed total torsion.


## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$.

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$. Moreover, we can prove that there exists a parallel normal subbundle which contains the first normal space.

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$. Moreover, we can prove that there exists a parallel normal subbundle which contains the first normal space. Then, we obtain

## Reduction Theorem [2]

A critical point of $\Theta$ must lie in a 3-dimensional totally geodesic submanifold of $M_{r}^{n}(\rho)$.

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$. Moreover, we can prove that there exists a parallel normal subbundle which contains the first normal space. Then, we obtain

## Reduction Theorem [2]

A critical point of $\Theta$ must lie in a 3-dimensional totally geodesic submanifold of $M_{r}^{n}(\rho)$.

Thus, we are interested in studying critical curves in pseudo-Riemannian 3-space forms, $M_{r}^{3}(\rho)$.

## Euler-Lagrange Equations

The Euler-Lagrange equations for the curvature energy functional $\Theta(\gamma)=\int_{\gamma} \mathcal{F}(\kappa)+\mu \tau+\lambda$, acting on $\Omega_{p_{o} p_{1}}$ can be written as

$$
\begin{aligned}
\mu \kappa \tau & =\kappa(\mathcal{F}+\lambda)-\dot{\mathcal{F}}\left(\kappa^{2}-\varepsilon_{1} \varepsilon_{3} \tau^{2}+\varepsilon_{2} \rho\right)-\varepsilon_{1} \varepsilon_{2} \dot{\mathcal{F}}_{s s} \\
\mu \kappa_{s} & =-2 \varepsilon_{1} \varepsilon_{3} \tau \dot{\mathcal{F}}_{s}-\varepsilon_{1} \varepsilon_{3} \tau_{s} \dot{\mathcal{F}}
\end{aligned}
$$

## Euler-Lagrange Equations

The Euler-Lagrange equations for the curvature energy functional $\Theta(\gamma)=\int_{\gamma} \mathcal{F}(\kappa)+\mu \tau+\lambda$, acting on $\Omega_{p_{o} p_{1}}$ can be written as

$$
\begin{aligned}
\mu \kappa \tau & =\kappa(\mathcal{F}+\lambda)-\dot{\mathcal{F}}\left(\kappa^{2}-\varepsilon_{1} \varepsilon_{3} \tau^{2}+\varepsilon_{2} \rho\right)-\varepsilon_{1} \varepsilon_{2} \dot{\mathcal{F}}_{s s} \\
\mu \kappa_{s} & =-2 \varepsilon_{1} \varepsilon_{3} \tau \dot{\mathcal{F}}_{s}-\varepsilon_{1} \varepsilon_{3} \tau_{s} \dot{\mathcal{F}} .
\end{aligned}
$$

## Generalized Kirchhoff Centerlines ([1], [2])

Curves whose curvature and torsion satisfy above equations will be called generalized Kirchhoff centerlines.

## Euler-Lagrange Equations

The Euler-Lagrange equations for the curvature energy functional $\Theta(\gamma)=\int_{\gamma} \mathcal{F}(\kappa)+\mu \tau+\lambda$, acting on $\Omega_{p_{o} p_{1}}$ can be written as

$$
\begin{aligned}
\mu \kappa \tau & =\kappa(\mathcal{F}+\lambda)-\dot{\mathcal{F}}\left(\kappa^{2}-\varepsilon_{1} \varepsilon_{3} \tau^{2}+\varepsilon_{2} \rho\right)-\varepsilon_{1} \varepsilon_{2} \dot{\mathcal{F}}_{s s} \\
\mu \kappa_{s} & =-2 \varepsilon_{1} \varepsilon_{3} \tau \dot{\mathcal{F}}_{s}-\varepsilon_{1} \varepsilon_{3} \tau_{s} \dot{\mathcal{F}}
\end{aligned}
$$

## Generalized Kirchhoff Centerlines ([1], [2])

Curves whose curvature and torsion satisfy above equations will be called generalized Kirchhoff centerlines.

Thus, under suitable boundary conditions, generalized Kirchhoff centerlines are critical curves of our energy functionals.

## Killing Vector Fields

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position.

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position. That is, if the following equations hold

$$
W(v)(\bar{t}, 0)=W(\kappa)(\bar{t}, 0)=W(\tau)(\bar{t}, 0)=0
$$

and this is independent on the choice of the tangent variation of $\gamma$ to $W$.

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position. That is, if the following equations hold

$$
W(v)(\bar{t}, 0)=W(\kappa)(\bar{t}, 0)=W(\tau)(\bar{t}, 0)=0
$$

and this is independent on the choice of the tangent variation of $\gamma$ to $W$.

## Characterization of Centerlines ([1], [2])

The vector field $\mathcal{I}=\varepsilon_{1} \varepsilon_{3} \mu T+\dot{\mathcal{F}} B$ is a Killing vector field along $\gamma$, if and only if, $\gamma$ is a generalized Kirchhoff centerline.

## Binormal Evolution Surfaces

## Binormal Evolution Surfaces

1. Evolution of Curves

## Binormal Evolution Surfaces

1. Evolution of Curves
2. Binormal Evolution Surfaces

## Binormal Evolution Surfaces

1. Evolution of Curves
2. Binormal Evolution Surfaces
3. Fundamental Equations

## Evolution of Curves

Every non-totally geodesic surface of $M_{r}^{3}(\rho)$ can be seen as the evolution of a Frenet curve of rank 2 or 3 under

$$
x_{t}=\Phi x_{s} \times \widetilde{\nabla}_{x_{s}} x_{s}
$$

## Evolution of Curves

Every non-totally geodesic surface of $M_{r}^{3}(\rho)$ can be seen as the evolution of a Frenet curve of rank 2 or 3 under

$$
x_{t}=\Phi x_{s} \times \widetilde{\nabla}_{x_{s}} x_{s}
$$

In order to endow this evolution with a geometrical meaning, we are going to consider that $\Phi=f\left(\left|\widetilde{\nabla}_{x_{s}} x_{s}\right|\right)$.

## Evolution of Curves

Every non-totally geodesic surface of $M_{r}^{3}(\rho)$ can be seen as the evolution of a Frenet curve of rank 2 or 3 under

$$
x_{t}=\Phi x_{s} \times \widetilde{\nabla}_{x_{s}} x_{s} .
$$

In order to endow this evolution with a geometrical meaning, we are going to consider that $\Phi=f\left(\left|\widetilde{\nabla}_{x_{s}} x_{s}\right|\right)$. Then, we have

## Properties ([1], [2])

1. This is a length-preserving evolution.

## Evolution of Curves

Every non-totally geodesic surface of $M_{r}^{3}(\rho)$ can be seen as the evolution of a Frenet curve of rank 2 or 3 under

$$
x_{t}=\Phi x_{s} \times \widetilde{\nabla}_{x_{s}} x_{s} .
$$

In order to endow this evolution with a geometrical meaning, we are going to consider that $\Phi=f\left(\left|\widetilde{\nabla}_{x_{s}} x_{s}\right|\right)$. Then, we have

## Properties ([1], [2])

1. This is a length-preserving evolution.
2. The initial condition $\gamma(s)=x(s, 0)$ evolves by the binormal flow, $x_{t}=\dot{P}(\kappa) B$, where $\dot{P}=\varepsilon_{2} \varepsilon_{3} \kappa f(\kappa)$.

## Binormal Evolution Surfaces

## Binormal Evolution Surfaces ([1], [2])

The corresponding immersed surface $(U, x)$ in $M_{r}^{3}(\rho)$ swept out by $\gamma(s)$ will be denoted $S_{\gamma}$ and called a binormal evolution surface with initial condition $\gamma$ and velocity $\dot{P}$.

## Binormal Evolution Surfaces

## Binormal Evolution Surfaces ([1], [2])

The corresponding immersed surface $(U, x)$ in $M_{r}^{3}(\rho)$ swept out by $\gamma(s)$ will be denoted $S_{\gamma}$ and called a binormal evolution surface with initial condition $\gamma$ and velocity $\dot{P}$.

We parametrize it by $x(s, t)=\gamma^{t}(s)$

## Binormal Evolution Surfaces

## Binormal Evolution Surfaces ([1], [2])

The corresponding immersed surface $(U, x)$ in $M_{r}^{3}(\rho)$ swept out by $\gamma(s)$ will be denoted $S_{\gamma}$ and called a binormal evolution surface with initial condition $\gamma$ and velocity $\dot{P}$.

We parametrize it by $x(s, t)=\gamma^{t}(s)$, to obtain

1. The metric of $S_{\gamma}$

$$
g=\varepsilon_{1} d s^{2}+\varepsilon_{3} \dot{P}^{2} d t^{2}
$$

## Binormal Evolution Surfaces

## Binormal Evolution Surfaces ([1], [2])

The corresponding immersed surface $(U, x)$ in $M_{r}^{3}(\rho)$ swept out by $\gamma(s)$ will be denoted $S_{\gamma}$ and called a binormal evolution surface with initial condition $\gamma$ and velocity $\dot{P}$.

We parametrize it by $x(s, t)=\gamma^{t}(s)$, to obtain

1. The metric of $S_{\gamma}$

$$
g=\varepsilon_{1} d s^{2}+\varepsilon_{3} \dot{P}^{2} d t^{2}
$$

2. The Gaussian curvature of $S_{\gamma}$

$$
K:=-\varepsilon_{1} \frac{\dot{P}_{s s}}{\dot{P}}
$$

## Binormal Evolution Surfaces

## Binormal Evolution Surfaces ([1], [2])

The corresponding immersed surface $(U, x)$ in $M_{r}^{3}(\rho)$ swept out by $\gamma(s)$ will be denoted $S_{\gamma}$ and called a binormal evolution surface with initial condition $\gamma$ and velocity $\dot{P}$.

We parametrize it by $x(s, t)=\gamma^{t}(s)$, to obtain

1. The metric of $S_{\gamma}$

$$
g=\varepsilon_{1} d s^{2}+\varepsilon_{3} \dot{P}^{2} d t^{2}
$$

2. The Gaussian curvature of $S_{\gamma}$

$$
K:=-\varepsilon_{1} \frac{\dot{P}_{s s}}{\dot{P}}
$$

3. The second fundamental form of $S_{\gamma}$

$$
\varepsilon_{2} h=-\kappa d s^{2}+2 \tau \dot{P} d s d t+\varepsilon_{2} \dot{P}^{2} h_{22} d t^{2}
$$

## Fundamental Equations

The term $h_{22}$ is defined by

$$
h_{22}=\left\langle\widetilde{\nabla}_{e_{2}} e_{2}, e_{3}\right\rangle=\frac{1}{\kappa}\left\{\varepsilon_{3} \frac{\dot{P}_{s s}}{\dot{P}}-\varepsilon_{2} \tau^{2}+\varepsilon_{1} \varepsilon_{3} \rho\right\} .
$$

## Fundamental Equations

The term $h_{22}$ is defined by

$$
h_{22}=\left\langle\widetilde{\nabla}_{e_{2}} e_{2}, e_{3}\right\rangle=\frac{1}{\kappa}\left\{\varepsilon_{3} \frac{\dot{P}_{s s}}{\dot{P}}-\varepsilon_{2} \tau^{2}+\varepsilon_{1} \varepsilon_{3} \rho\right\} .
$$

Using this, we see that the Gauss-Codazzi equations boil down to

$$
\begin{aligned}
\kappa_{t} & =-2 \dot{P}_{s} \tau-\tau_{s} \dot{P} \\
\varepsilon_{3} \tau_{t} & =\left(\frac{1}{\kappa}\left(\varepsilon_{2} \dot{P}_{s s}+\varepsilon_{1} \dot{P}\left(\kappa^{2}-\varepsilon_{1} \varepsilon_{3} \tau^{2}+\varepsilon_{2} \rho\right)-\varepsilon_{1} \kappa P\right)\right)_{s}
\end{aligned}
$$

## Fundamental Equations

The term $h_{22}$ is defined by

$$
h_{22}=\left\langle\widetilde{\nabla}_{e_{2}} e_{2}, e_{3}\right\rangle=\frac{1}{\kappa}\left\{\varepsilon_{3} \frac{\dot{P}_{s s}}{\dot{P}}-\varepsilon_{2} \tau^{2}+\varepsilon_{1} \varepsilon_{3} \rho\right\} .
$$

Using this, we see that the Gauss-Codazzi equations boil down to

$$
\begin{aligned}
\kappa_{t} & =-2 \dot{P}_{s} \tau-\tau_{s} \dot{P} \\
\varepsilon_{3} \tau_{t} & =\left(\frac{1}{\kappa}\left(\varepsilon_{2} \dot{P}_{s s}+\varepsilon_{1} \dot{P}\left(\kappa^{2}-\varepsilon_{1} \varepsilon_{3} \tau^{2}+\varepsilon_{2} \rho\right)-\varepsilon_{1} \kappa P\right)\right)_{s}
\end{aligned}
$$

## Fundamental Theorem of Submanifolds ([1], [2])

For any pair of functions $\kappa(s, t), \tau(s, t)$ satisfying the Gauss-Codazzi equations, there exists an isometric immersion $x: U \rightarrow M_{r}^{3}(\rho)$ foliated by a family of geodesics $\gamma^{t}(s)=x(s, t)$ evolving by the binormal flow.

## Travelling Wave Solutions

## Travelling Wave Solutions

\author{

1. Travelling Wave Solutions
}

## Travelling Wave Solutions

1. Travelling Wave Solutions
2. Foliations of Binormal Evolution Surfaces

## Travelling Wave Solutions

1. Travelling Wave Solutions
2. Foliations of Binormal Evolution Surfaces
3. Applications

## Travelling Wave Solutions

A travelling wave is a function $u(x, t)=f(x-\eta t), \eta \in \mathbb{R}$ for some smooth function $f$,

## Travelling Wave Solutions

A travelling wave is a function $u(x, t)=f(x-\eta t), \eta \in \mathbb{R}$ for some smooth function $f$, that is we are considering travelling waves with wave number 1 and velocity (frequency) $\eta$.

## Travelling Wave Solutions

A travelling wave is a function $u(x, t)=f(x-\eta t), \eta \in \mathbb{R}$ for some smooth function $f$, that is we are considering travelling waves with wave number 1 and velocity (frequency) $\eta$.

Travelling Wave Solutions of Gauss-Codazzi Equations ([1], [2])

They correspond to the curvature and torsion of generalized Kirchhoff centerlines.

## Travelling Wave Solutions

A travelling wave is a function $u(x, t)=f(x-\eta t), \eta \in \mathbb{R}$ for some smooth function $f$, that is we are considering travelling waves with wave number 1 and velocity (frequency) $\eta$.

## Travelling Wave Solutions of Gauss-Codazzi Equations ([1], [2])

They correspond to the curvature and torsion of generalized Kirchhoff centerlines.Moreover, generalized Kirchhoff centerlines evolve following the binormal flow by isometries of $M_{r}^{3}(\rho)$ and slippery.

## Foliations of BES

Thus, we have

1. A geodesic foliation $\mathcal{F}=\left\{\gamma^{t}\right\}_{t \in \mathbb{R}}$ of $S_{\gamma}$.

## Foliations of BES

Thus, we have

1. A geodesic foliation $\mathcal{F}=\left\{\gamma^{t}\right\}_{t \in \mathbb{R}}$ of $S_{\gamma}$.
2. An everywhere orthogonal foliation $\mathcal{F}^{\perp}=\left\{\delta_{s}\right\}_{s \in J}$, consisting on integral curves of $x_{t}$

## Foliations of BES

Thus, we have

1. A geodesic foliation $\mathcal{F}=\left\{\gamma^{t}\right\}_{t \in \mathbb{R}}$ of $S_{\gamma}$.
2. An everywhere orthogonal foliation $\mathcal{F}^{\perp}=\left\{\delta_{s}\right\}_{s \in J}$, consisting on integral curves of $x_{t}$ (this curves have constant curvature in $S_{\gamma}$ ).

## Foliations of BES

Thus, we have

1. A geodesic foliation $\mathcal{F}=\left\{\gamma^{t}\right\}_{t \in \mathbb{R}}$ of $S_{\gamma}$.
2. An everywhere orthogonal foliation $\mathcal{F}^{\perp}=\left\{\delta_{s}\right\}_{s \in J}$, consisting on integral curves of $x_{t}$ (this curves have constant curvature in $S_{\gamma}$ ).

## Theorem [2]

Consider the pseudo-Riemannian manifold ( $B \times F, g$ ), whose canonical foliations $\mathcal{F}_{B}$ and $\mathcal{F}_{F}$ are orthogonal everywhere. Then, the metric $g$ is a warped product metric, if and only if, $\mathcal{F}_{B}$ is a totally geodesic foliation and $\mathcal{F}_{F}$ is a spherical foliation.

## Applications

## Applications

1. Hasimoto Surfaces

- O. J. Garay, A. Pámpano and C. Woo, Hypersurface constrained elasticae in Lorentzian space forms, Advances in Mathematical Physics 2015, 2015, Article ID 458178, 13 pp.
- H. Hasimoto, A soliton on a vortex filament, J. Fluid Mech. 51, 1972, pp. 477-485.


## Applications

1. Hasimoto Surfaces

- O. J. Garay, A. Pámpano and C. Woo, Hypersurface constrained elasticae in Lorentzian space forms, Advances in Mathematical Physics 2015, 2015, Article ID 458178, 13 pp.
- H. Hasimoto, A soliton on a vortex filament, J. Fluid Mech. 51, 1972, pp. 477-485.

2. Hopf Cylinders

- M. Barros, A. Ferrández, M.A. Javaloyes and P. Lucas, Relativistic particles with rigidity and torsion in $D=3$ spacetimes, Class. Quantum Grav. 22, pp. 489-513, 2005.


## Applications

1. Hasimoto Surfaces

- O. J. Garay, A. Pámpano and C. Woo, Hypersurface constrained elasticae in Lorentzian space forms, Advances in Mathematical Physics 2015, 2015, Article ID 458178, 13 pp.
- H. Hasimoto, A soliton on a vortex filament, J. Fluid Mech. 51, 1972, pp. 477-485.

2. Hopf Cylinders

- M. Barros, A. Ferrández, M.A. Javaloyes and P. Lucas, Relativistic particles with rigidity and torsion in $D=3$ spacetimes, Class. Quantum Grav. 22, pp. 489-513, 2005.

3. Constant Mean Curvature BES

- W. Blaschke, Vorlesungen über Differentialgeometrie und geometrische Grundlagen von Einsteins Relativittstheorie I: Elementare Differentialgeometrie, Springer, Berlin, 1930.
- O. J. Garay and A. Pámpano, On a Blaschke's variational problem. In preparation, 2017.


## References

1. O. J. Garay, A. Pámpano, Binormal Evolution of Curves with Prescribed Velocity, WSEAS transactions on fluid mechanics 11, 2016, pp. 112-120.
2. O. J. Garay and A. Pámpano, Travelling Wave Solutions of the Extended Codazzi-Betchov-Da Rios Evolution Equations, In preparation, 2017.

## The End

