# Constant Mean Curvature Invariant Surfaces in $\mathbb{L}^{3}$ and a Blaschke's Variational Problem 

## Álvaro Pámpano Llarena

Young Researcher Workshop on Differential Geometry in Minkowski Space

Granada, April 17-20, 2017

## Objective

## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

- Evolve these critical curves under their associated Killing.


## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

- Evolve these critical curves under their associated Killing.
- The generated surfaces $S_{\gamma}$ have CMC.


## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

- Evolve these critical curves under their associated Killing.
- The generated surfaces $S_{\gamma}$ have CMC.

Objective 2 (CMC Invariant Surfaces)
Characterize constant mean curvature $\xi$-invariant surfaces $S$ of $\mathbb{L}^{3}$.

## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

- Evolve these critical curves under their associated Killing.
- The generated surfaces $S_{\gamma}$ have CMC.


## Objective 2 (CMC Invariant Surfaces)

Characterize constant mean curvature $\xi$-invariant surfaces $S$ of $\mathbb{L}^{3}$.
For this purpose,

- Get a geodesic foliation of $S$.


## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

- Evolve these critical curves under their associated Killing.
- The generated surfaces $S_{\gamma}$ have CMC.


## Objective 2 (CMC Invariant Surfaces)

Characterize constant mean curvature $\xi$-invariant surfaces $S$ of $\mathbb{L}^{3}$.
For this purpose,

- Get a geodesic foliation of $S$.
- Leaves are critical for the Blaschke's problem.


## Objective

## Objective 1 (Extended Blaschke's Problem)

Completely solve an extended Blaschke's Variational problem in the Minkowski $n$-space, $\mathbb{L}^{n}$.

Then, following the idea of [3] and [4],

- Evolve these critical curves under their associated Killing.
- The generated surfaces $S_{\gamma}$ have CMC.


## Objective 2 (CMC Invariant Surfaces)

Characterize constant mean curvature $\xi$-invariant surfaces $S$ of $\mathbb{L}^{3}$.
For this purpose,

- Get a geodesic foliation of $S$.
- Leaves are critical for the Blaschke's problem.
- Finally, study isometric deformations.

Index

## Index

1. Extension of a Blaschke's Variational Problem

## Index

1. Extension of a Blaschke's Variational Problem
2. Constant Mean Curvature Invariant Surfaces

## Index

1. Extension of a Blaschke's Variational Problem
2. Constant Mean Curvature Invariant Surfaces
3. Isometric Deformations of These Surfaces

## Extension of Blaschke's Problem

## Extension of Blaschke's Problem

1. Curvature Energy Functional

## Extension of Blaschke's Problem

1. Curvature Energy Functional
2. Reduction Theorem

## Extension of Blaschke's Problem

1. Curvature Energy Functional
2. Reduction Theorem
3. Euler-Lagrange Equations

## Extension of Blaschke's Problem

1. Curvature Energy Functional
2. Reduction Theorem
3. Euler-Lagrange Equations
4. Critical Curves

## Extension of Blaschke's Problem

1. Curvature Energy Functional
2. Reduction Theorem
3. Euler-Lagrange Equations
4. Critical Curves
5. Planar Critical Curves

## Curvature Energy Functional

- We denote by $\Omega_{p_{0} p_{1}}$ the space of smooth immersed curves of $\mathbb{L}^{n}$ joining two points of it, and verifying that $\kappa-\mu>0$.


## Curvature Energy Functional

- We denote by $\Omega_{p_{o} p_{1}}$ the space of smooth immersed curves of $\mathbb{L}^{n}$ joining two points of it, and verifying that $\kappa-\mu>0$.
- We are going to consider the curvature energy functional acting on $\Omega_{p_{o} p_{1}}$

$$
\Theta(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu}=\int_{0}^{L} \sqrt{\kappa(s)-\mu} d s
$$

where $\mu \in \mathbb{R}$ is a fixed real constant.

## Curvature Energy Functional

- We denote by $\Omega_{p_{0} p_{1}}$ the space of smooth immersed curves of $\mathbb{L}^{n}$ joining two points of it, and verifying that $\kappa-\mu>0$.
- We are going to consider the curvature energy functional acting on $\Omega_{p_{o} p_{1}}$

$$
\Theta(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu}=\int_{0}^{L} \sqrt{\kappa(s)-\mu} d s
$$

where $\mu \in \mathbb{R}$ is a fixed real constant.

- Take into account that $\kappa=\mu$ would be a global minimum if we were considering $L^{1}([0, L])$ as the space of curves.


## Curvature Energy Functional

- We denote by $\Omega_{p_{o} p_{1}}$ the space of smooth immersed curves of $\mathbb{L}^{n}$ joining two points of it, and verifying that $\kappa-\mu>0$.
- We are going to consider the curvature energy functional acting on $\Omega_{p_{o} p_{1}}$

$$
\Theta(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu}=\int_{0}^{L} \sqrt{\kappa(s)-\mu} d s
$$

where $\mu \in \mathbb{R}$ is a fixed real constant.

- Take into account that $\kappa=\mu$ would be a global minimum if we were considering $L^{1}([0, L])$ as the space of curves.
- Observe that the case $\mu=0$ was studied by Blaschke in the Euclidean 3-Space, [2].


## Reduction Theorem

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$.

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$. Moreover, we can prove that there exists a parallel normal subbundle which contains the first normal space.

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$. Moreover, we can prove that there exists a parallel normal subbundle which contains the first normal space. Then, we obtain

## Reduction Theorem ([1])

A critical point of $\Theta$ must lie in a 3-dimensional totally geodesic submanifold of $\mathbb{L}^{n}$.

## Reduction Theorem

From the first variation formula and the Frenet-Serret equations we get that rank $\gamma \leq 3$. Moreover, we can prove that there exists a parallel normal subbundle which contains the first normal space. Then, we obtain

## Reduction Theorem ([1])

A critical point of $\Theta$ must lie in a 3-dimensional totally geodesic submanifold of $\mathbb{L}^{n}$.

Thus, we are interested in studying critical curves in the Minkowski 3 -Space, $\mathbb{L}^{3}$.

## Euler-Lagrange Equations

## Euler-Lagrange Equations

The Euler-Lagrange equations for the curvature energy functional $\Theta(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu}$, in $\mathbb{L}^{3}$ can be written as

$$
\begin{aligned}
\frac{d^{2}}{d s^{2}}\left(\frac{\varepsilon_{2}}{\sqrt{\kappa-\mu}}\right)+\frac{1}{\sqrt{\kappa-\mu}}\left(\varepsilon_{1} \kappa^{2}-\varepsilon_{3} \tau^{2}\right) & =2 \varepsilon_{1} \kappa \sqrt{\kappa-\mu} \\
\frac{d}{d s}\left(\frac{\tau}{\kappa-\mu}\right) & =0
\end{aligned}
$$

## Euler-Lagrange Equations

The Euler-Lagrange equations for the curvature energy functional $\Theta(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu}$, in $\mathbb{L}^{3}$ can be written as

$$
\begin{aligned}
\frac{d^{2}}{d s^{2}}\left(\frac{\varepsilon_{2}}{\sqrt{\kappa-\mu}}\right)+\frac{1}{\sqrt{\kappa-\mu}}\left(\varepsilon_{1} \kappa^{2}-\varepsilon_{3} \tau^{2}\right) & =2 \varepsilon_{1} \kappa \sqrt{\kappa-\mu} \\
\frac{d}{d s}\left(\frac{\tau}{\kappa-\mu}\right) & =0 .
\end{aligned}
$$

Under suitable boundary conditions, solutions of these equations are critical curves for our energy functional.

## Solutions with Constant Curvature

- Consider that the curvature is constant, $\kappa=\kappa_{o} \in \mathbb{R}^{+}$.


## Solutions with Constant Curvature

- Consider that the curvature is constant, $\kappa=\kappa_{o} \in \mathbb{R}^{+}$.
- Then the second Euler-Lagrange equation

$$
\frac{d}{d s}\left(\frac{\tau}{\kappa-\mu}\right)=0
$$

implies that the torsion is constant, that is, $\tau=\tau_{o} \in \mathbb{R}^{+}$.

## Solutions with Constant Curvature

- Consider that the curvature is constant, $\kappa=\kappa_{o} \in \mathbb{R}^{+}$.
- Then the second Euler-Lagrange equation

$$
\frac{d}{d s}\left(\frac{\tau}{\kappa-\mu}\right)=0
$$

implies that the torsion is constant, that is, $\tau=\tau_{o} \in \mathbb{R}^{+}$.

- Thus, $\gamma$ must be a Frenet helix.


## Solutions with Constant Curvature

- Consider that the curvature is constant, $\kappa=\kappa_{o} \in \mathbb{R}^{+}$.
- Then the second Euler-Lagrange equation

$$
\frac{d}{d s}\left(\frac{\tau}{\kappa-\mu}\right)=0
$$

implies that the torsion is constant, that is, $\tau=\tau_{o} \in \mathbb{R}^{+}$.

- Thus, $\gamma$ must be a Frenet helix.
- Moreover, substituting this in the first Euler-Lagrange equation we get the relation

$$
\kappa_{o}=\mu+\sqrt{\mu^{2}-\varepsilon_{1} \varepsilon_{3} \tau_{o}^{2}}
$$

## Solutions with Non-Constant Curvature

Suppose now that the curvature is not constant,

## Solutions with Non-Constant Curvature

Suppose now that the curvature is not constant, then let's call

$$
\begin{aligned}
a & =-\varepsilon_{1} \varepsilon_{2} \mu^{2} \\
b & =4 \varepsilon_{2} d+2 \varepsilon_{1} \varepsilon_{2} \mu \\
c & =-\varepsilon_{1} \varepsilon_{2}-\varepsilon_{2} \varepsilon_{3} e^{2}
\end{aligned}
$$

and $\Delta=4 a c-b^{2}=-16 d^{2}-16 \varepsilon_{1} \mu d+4 \varepsilon_{1} \varepsilon_{3} \mu^{2} e^{2}$, where $d$, e are real constants (constants of integration).

## Solutions with Non-Constant Curvature

Suppose now that the curvature is not constant, then let's call

$$
\begin{aligned}
a & =-\varepsilon_{1} \varepsilon_{2} \mu^{2} \\
b & =4 \varepsilon_{2} d+2 \varepsilon_{1} \varepsilon_{2} \mu \\
c & =-\varepsilon_{1} \varepsilon_{2}-\varepsilon_{2} \varepsilon_{3} e^{2}
\end{aligned}
$$

and $\Delta=4 a c-b^{2}=-16 d^{2}-16 \varepsilon_{1} \mu d+4 \varepsilon_{1} \varepsilon_{3} \mu^{2} e^{2}$, where $d$, e are real constants (constants of integration). Then, calling $x=\kappa-\mu$, the first integrals of the Euler-Lagrange equations reduce to

$$
\begin{aligned}
x_{s}^{2} & =4 x^{2}\left(c x^{2}+b x+a\right) \\
\tau & =e x
\end{aligned}
$$

## Solutions with Non-Constant Curvature

Suppose now that the curvature is not constant, then let's call

$$
\begin{aligned}
a & =-\varepsilon_{1} \varepsilon_{2} \mu^{2} \\
b & =4 \varepsilon_{2} d+2 \varepsilon_{1} \varepsilon_{2} \mu \\
c & =-\varepsilon_{1} \varepsilon_{2}-\varepsilon_{2} \varepsilon_{3} e^{2},
\end{aligned}
$$

and $\Delta=4 a c-b^{2}=-16 d^{2}-16 \varepsilon_{1} \mu d+4 \varepsilon_{1} \varepsilon_{3} \mu^{2} e^{2}$, where $d$, e are real constants (constants of integration). Then, calling $x=\kappa-\mu$, the first integrals of the Euler-Lagrange equations reduce to

$$
\begin{aligned}
x_{s}^{2} & =4 x^{2}\left(c x^{2}+b x+a\right) \\
\tau & =e x
\end{aligned}
$$

Thus, the following cases are not possible:

1. $\Delta \geq 0$ and $c<0$,
2. $a \leq 0,2 d=-\varepsilon_{1} \mu$ and $e^{2}=-\varepsilon_{1} \varepsilon_{3}$.

## Solutions with Non-Constant Curvature

We can integrate the first integrals of Euler-Lagrange equations, and get the curvature of the critical curves, in the other cases.

## Solutions with Non-Constant Curvature

We can integrate the first integrals of Euler-Lagrange equations, and get the curvature of the critical curves, in the other cases.

1. If $\Delta \neq 0$ and $a \neq 0$

$$
\kappa(s)=\frac{2 a+\mu(b+\sqrt{|\Delta|} f(2 \mu s))}{-b+\sqrt{|\Delta|} f(2 \mu s)}
$$

where, $f(x)=\sinh x$, if $\Delta>0$ and $a>0 ; f(x)=\cosh x$, if $\Delta<0$ and $a>0$; and $f(x)=\sin x$, if $\Delta<0$ and $a<0$.

## Solutions with Non-Constant Curvature

2. If $\Delta=0$ and $a>0$

$$
k(s)=\frac{\mu+(2 a-b \mu) \exp 2 \mu s}{1-b \exp 2 \mu s} .
$$

## Solutions with Non-Constant Curvature

2. If $\Delta=0$ and $a>0$

$$
k(s)=\frac{\mu+(2 a-b \mu) \exp 2 \mu s}{1-b \exp 2 \mu s} .
$$

3. If $\Delta<0$ and $a=0$, that is, $(\mu=0)$

$$
k(s)=\frac{b}{-c+b^{2} s^{2}}
$$

## Solutions with Non-Constant Curvature

2. If $\Delta=0$ and $a>0$

$$
k(s)=\frac{\mu+(2 a-b \mu) \exp 2 \mu s}{1-b \exp 2 \mu s} .
$$

3. If $\Delta<0$ and $a=0$, that is, $(\mu=0)$

$$
k(s)=\frac{b}{-c+b^{2} s^{2}}
$$

4. If $\Delta=0$ and $a=0$, that is, $(\mu=d=0)$

$$
k(s)=\frac{1}{2 \sqrt{c} s} .
$$

## Critical Curves

## Critical Curves

Observe that, in all the cases, the torsion of the solutions is given by

$$
\tau=e(\kappa-\mu)
$$

where $e \in \mathbb{R}$ is one of the constants of integration.

## Critical Curves

Observe that, in all the cases, the torsion of the solutions is given by

$$
\tau=e(\kappa-\mu)
$$

where $e \in \mathbb{R}$ is one of the constants of integration.

## Fundamental Theorem of Curves in $\mathbb{L}^{3}$

The curvature and torsion (together with the causal characters $\varepsilon_{i}$ of the Frenet frame) determine a unique curve up to rigid motions.

## Critical Curves

Observe that, in all the cases, the torsion of the solutions is given by

$$
\tau=e(\kappa-\mu)
$$

where $e \in \mathbb{R}$ is one of the constants of integration.

## Fundamental Theorem of Curves in $\mathbb{L}^{3}$

The curvature and torsion (together with the causal characters $\varepsilon_{i}$ of the Frenet frame) determine a unique curve up to rigid motions.

- When $\mu=0$, our critical curves are Lancret curves, that is, curves making a constant angle with a fixed direction.


## Critical Curves

Observe that, in all the cases, the torsion of the solutions is given by

$$
\tau=e(\kappa-\mu)
$$

where $e \in \mathbb{R}$ is one of the constants of integration.

## Fundamental Theorem of Curves in $\mathbb{L}^{3}$

The curvature and torsion (together with the causal characters $\varepsilon_{i}$ of the Frenet frame) determine a unique curve up to rigid motions.

- When $\mu=0$, our critical curves are Lancret curves, that is, curves making a constant angle with a fixed direction.
- On the other hand, if $\mu \neq 0$, our critical curves are Bertrand curves.


## Planar Critical Curves

## Planar Critical Curves

Take $\tau=0$, and suppose that $\gamma$ lies in a Riemannian plane, $\gamma \subset \mathbb{R}^{2}$,

## Planar Critical Curves

Take $\tau=0$, and suppose that $\gamma$ lies in a Riemannian plane, $\gamma \subset \mathbb{R}^{2}$, then we have

Delaunay Curves ([1], [3])
Critical curves of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ in $\mathbb{R}^{2}$ are precisely the Delaunay curves, that is, the roulettes of foci of conics (lines, circles, catenaries, nodaries and undularies).

## Planar Critical Curves

Take $\tau=0$, and suppose that $\gamma$ lies in a Riemannian plane, $\gamma \subset \mathbb{R}^{2}$, then we have

Delaunay Curves ([1], [3])
Critical curves of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ in $\mathbb{R}^{2}$ are precisely the Delaunay curves, that is, the roulettes of foci of conics (lines, circles, catenaries, nodaries and undularies).

If $\gamma$ lies in a Lorentzian plane, $\gamma \subset \mathbb{L}^{2}$,

## Planar Critical Curves

Take $\tau=0$, and suppose that $\gamma$ lies in a Riemannian plane, $\gamma \subset \mathbb{R}^{2}$, then we have

## Delaunay Curves ([1], [3])

Critical curves of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ in $\mathbb{R}^{2}$ are precisely the Delaunay curves, that is, the roulettes of foci of conics (lines, circles, catenaries, nodaries and undularies).

If $\gamma$ lies in a Lorentzian plane, $\gamma \subset \mathbb{L}^{2}$, we can prove

## Hano-Nomizu Curves ([1], [5])

The locus of the origin when a part of a spacelike quadratic curve is rolled along a spacelike line is a spacelike critical curve for $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ in $\mathbb{L}^{2}$.

## CMC Invariant Surfaces

## CMC Invariant Surfaces

1. Killing Vector Fields

## CMC Invariant Surfaces

1. Killing Vector Fields
2. Evolution of Critical Curves

## CMC Invariant Surfaces

1. Killing Vector Fields
2. Evolution of Critical Curves
3. Geodesic Foliations of Invariant Surfaces

## Killing Vector Fields

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position.

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position. That is, if the following equations hold

$$
W(v)(\bar{t}, 0)=W(\kappa)(\bar{t}, 0)=W(\tau)(\bar{t}, 0)=0
$$

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position. That is, if the following equations hold

$$
W(v)(\bar{t}, 0)=W(\kappa)(\bar{t}, 0)=W(\tau)(\bar{t}, 0)=0
$$

Let's consider the functional $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ acting on the space $\Omega_{p_{o} p_{1}}$, then

Associated Killing Vector Field along $\gamma$ ([3])

## Killing Vector Fields

A vector field $W$ along $\gamma$, which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along $\gamma$ if it evolves in the direction of $W$ without changing shape, only position. That is, if the following equations hold

$$
W(v)(\bar{t}, 0)=W(\kappa)(\bar{t}, 0)=W(\tau)(\bar{t}, 0)=0
$$

Let's consider the functional $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ acting on the space $\Omega_{p_{o} p_{1}}$, then

## Associated Killing Vector Field along $\gamma$ ([3])

The vector field $\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B$ is a Killing vector field along $\gamma$, if and only if, $\gamma$ verifies the Euler-Lagrange equations ( $\gamma$ may have a restriction on its length).

## Evolution of Critical Curves

Since $\mathbb{L}^{3}$ is complete,

1. Consider the one-parameter group of isometries determined by the flow of

$$
\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B
$$

that is, $\left\{\phi_{t}, t \in \mathbb{R}\right\}$.

## Evolution of Critical Curves

Since $\mathbb{L}^{3}$ is complete,

1. Consider the one-parameter group of isometries determined by the flow of

$$
\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B
$$

that is, $\left\{\phi_{t}, t \in \mathbb{R}\right\}$.
2. Now, consider the surface $S_{\gamma}:=\left\{x(s, t):=\phi_{t}(\gamma(s))\right\}$.

## Evolution of Critical Curves

Since $\mathbb{L}^{3}$ is complete,

1. Consider the one-parameter group of isometries determined by the flow of

$$
\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B
$$

that is, $\left\{\phi_{t}, t \in \mathbb{R}\right\}$.
2. Now, consider the surface $S_{\gamma}:=\left\{x(s, t):=\phi_{t}(\gamma(s))\right\}$.

3 . The surface $S_{\gamma}$ is a $\mathcal{I}$-invariant surface

## Evolution of Critical Curves

Since $\mathbb{L}^{3}$ is complete,

1. Consider the one-parameter group of isometries determined by the flow of

$$
\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B
$$

that is, $\left\{\phi_{t}, t \in \mathbb{R}\right\}$.
2. Now, consider the surface $S_{\gamma}:=\left\{x(s, t):=\phi_{t}(\gamma(s))\right\}$.
3. The surface $S_{\gamma}$ is a $\mathcal{I}$-invariant surface whose mean curvature is

$$
H=-\varepsilon_{1} \varepsilon_{2} \mu .
$$

## Evolution of Critical Curves

Since $\mathbb{L}^{3}$ is complete,

1. Consider the one-parameter group of isometries determined by the flow of

$$
\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B
$$

that is, $\left\{\phi_{t}, t \in \mathbb{R}\right\}$.
2. Now, consider the surface $S_{\gamma}:=\left\{x(s, t):=\phi_{t}(\gamma(s))\right\}$.
3. The surface $S_{\gamma}$ is a $\mathcal{I}$-invariant surface whose mean curvature is

$$
H=-\varepsilon_{1} \varepsilon_{2} \mu .
$$

4. As $\mu \in \mathbb{R}$ is fixed, $S_{\gamma}$ has constant mean curvature.

## Evolution of Critical Curves

Since $\mathbb{L}^{3}$ is complete,

1. Consider the one-parameter group of isometries determined by the flow of

$$
\mathcal{I}=\frac{1}{2 \sqrt{\kappa-\mu}} B
$$

that is, $\left\{\phi_{t}, t \in \mathbb{R}\right\}$.
2. Now, consider the surface $S_{\gamma}:=\left\{x(s, t):=\phi_{t}(\gamma(s))\right\}$.
3. The surface $S_{\gamma}$ is a $\mathcal{I}$-invariant surface whose mean curvature is

$$
H=-\varepsilon_{1} \varepsilon_{2} \mu .
$$

4. As $\mu \in \mathbb{R}$ is fixed, $S_{\gamma}$ has constant mean curvature.

## Foliations of Invariant Surfaces

For the converse, assume that $S$ is a non-degenerate $\mathcal{G}_{\xi}$-invariant surface of $\mathbb{L}^{3}$, i.e., for any $x \in S$ and $\Phi_{t} \in \mathcal{G}_{\xi}$ we have $\Phi_{t}(S)=S$.

## Foliations of Invariant Surfaces

For the converse, assume that $S$ is a non-degenerate $\mathcal{G}_{\xi}$-invariant surface of $\mathbb{L}^{3}$, i.e., for any $x \in S$ and $\Phi_{t} \in \mathcal{G}_{\xi}$ we have $\Phi_{t}(S)=S$.

Geodesic Foliation by Critical Curves ([1])
A $\xi$-invariant CMC surface $S$ of $\mathbb{L}^{3}$ admits a local geodesic parametrization where the leaves provide a geodesic foliation by critical curves of the extended Blaschke's problem with $\mu=-\varepsilon_{1} \varepsilon_{2} H$.

## Foliations of Invariant Surfaces

For the converse, assume that $S$ is a non-degenerate $\mathcal{G}_{\xi}$-invariant surface of $\mathbb{L}^{3}$, i.e., for any $x \in S$ and $\Phi_{t} \in \mathcal{G}_{\xi}$ we have $\Phi_{t}(S)=S$.

Geodesic Foliation by Critical Curves ([1])
A $\xi$-invariant CMC surface $S$ of $\mathbb{L}^{3}$ admits a local geodesic parametrization where the leaves provide a geodesic foliation by critical curves of the extended Blaschke's problem with $\mu=-\varepsilon_{1} \varepsilon_{2} H$.

Thus, every $\xi$-invariant CMC surface is

- A ruled surface or,


## Foliations of Invariant Surfaces

For the converse, assume that $S$ is a non-degenerate $\mathcal{G}_{\xi}$-invariant surface of $\mathbb{L}^{3}$, i.e., for any $x \in S$ and $\Phi_{t} \in \mathcal{G}_{\xi}$ we have $\Phi_{t}(S)=S$.

Geodesic Foliation by Critical Curves ([1])
A $\xi$-invariant CMC surface $S$ of $\mathbb{L}^{3}$ admits a local geodesic parametrization where the leaves provide a geodesic foliation by critical curves of the extended Blaschke's problem with $\mu=-\varepsilon_{1} \varepsilon_{2} H$.

Thus, every $\xi$-invariant CMC surface is

- A ruled surface or,
- It is generated by evolving a critical curve of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa+\varepsilon_{1} \varepsilon_{2} H} d s$ under the flow of the Killing vector field $\xi$.


## Isometric Deformations

1. Deformations by Isometric Surfaces

## Isometric Deformations

1. Deformations by Isometric Surfaces
2. Orbits of Deformations

## Deformations by Isometric Surfaces (1)

Suppose that the critical curve $\gamma$ of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ has constant curvature $\kappa_{o}$

## Deformations by Isometric Surfaces (1)

Suppose that the critical curve $\gamma$ of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ has constant curvature $\kappa_{0}$, then we know that $\gamma$ is a Frenet helix with

$$
\begin{aligned}
\kappa & =\kappa_{o}=\mu+\sqrt{\mu^{2}-\varepsilon_{2} \varepsilon_{3} \tau_{o}^{2}} \\
\tau & =\tau_{o}
\end{aligned}
$$

## Deformations by Isometric Surfaces (1)

Suppose that the critical curve $\gamma$ of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$ has constant curvature $\kappa_{o}$, then we know that $\gamma$ is a Frenet helix with

$$
\begin{aligned}
\kappa & =\kappa_{o}=\mu+\sqrt{\mu^{2}-\varepsilon_{2} \varepsilon_{3} \tau_{o}^{2}} \\
\tau & =\tau_{o}
\end{aligned}
$$

and these helices can only generate congruence surfaces to the following ones (depending on the causal character of $\varepsilon_{i}$ )

(E) $\varepsilon_{1} \varepsilon_{2}=-1$

(F) $\varepsilon_{3}=-1$

## Deformations by Isometric Surfaces (2)

## Deformations by Isometric Surfaces (2)

If the following relations involving the constants $d$ and $e$,

1. If $\Delta \neq 0$ and $a \neq 0, \Delta=\nu b^{2}$,
2. If $\Delta=0$ and $a>0$, (this does not give an isometric deformation),
3. If $\Delta<0$ and $a=0, c=\nu b^{2}$ and
4. If $\Delta=a=0$, (as $d=0$, there is no biparametric family) there is no any constraint,
are verified for some $\nu \in \mathbb{R}$ and for each correpondent solution of the Euler-Lagrange equations

## Deformations by Isometric Surfaces (2)

If the following relations involving the constants $d$ and $e$,

1. If $\Delta \neq 0$ and $a \neq 0, \Delta=\nu b^{2}$,
2. If $\Delta=0$ and $a>0$, (this does not give an isometric deformation),
3. If $\Delta<0$ and $a=0, c=\nu b^{2}$ and
4. If $\Delta=a=0$, (as $d=0$, there is no biparametric family) there is no any constraint,
are verified for some $\nu \in \mathbb{R}$ and for each correpondent solution of the Euler-Lagrange equations, we can prove

## Isometric Deformations ([1])

For each real constant $\mu$, let $\left\{S_{\gamma}\right\}_{d, e}$ be the family of $\xi$-invariant surfaces shaped on a critical curve $\gamma$ of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$.

## Deformations by Isometric Surfaces (2)

If the following relations involving the constants $d$ and $e$,

1. If $\Delta \neq 0$ and $a \neq 0, \Delta=\nu b^{2}$,
2. If $\Delta=0$ and $a>0$, (this does not give an isometric deformation),
3. If $\Delta<0$ and $a=0, c=\nu b^{2}$ and
4. If $\Delta=a=0$, (as $d=0$, there is no biparametric family) there is no any constraint,
are verified for some $\nu \in \mathbb{R}$ and for each correpondent solution of the Euler-Lagrange equations, we can prove

## Isometric Deformations ([1])

For each real constant $\mu$, let $\left\{S_{\gamma}\right\}_{d, e}$ be the family of $\xi$-invariant surfaces shaped on a critical curve $\gamma$ of $\boldsymbol{\Theta}(\gamma)=\int_{\gamma} \sqrt{\kappa-\mu} d s$.Under the relations above (except for case 2), the family $\left\{S_{\gamma}\right\}_{d}$ is generated by isometric surfaces with the same constant mean curvature $H=-\varepsilon_{1} \varepsilon_{2} \mu$.

## Deformations of Riemannian CMC Surfaces

Let $S_{\gamma}$ be a Riemannian surface of $\mathbb{L}^{3}$,

## Deformations of Riemannian CMC Surfaces

Let $S_{\gamma}$ be a Riemannian surface of $\mathbb{L}^{3}$, then the orbits are

(I) $H=0$

(J) $H \neq 0$

## Deformations of Riemannian CMC Surfaces

Let $S_{\gamma}$ be a Riemannian surface of $\mathbb{L}^{3}$, then the orbits are

(k) $H=0$

(L) $H \neq 0$

Rotational Spacelike Surfaces ([1])
Any spacelike surface of CMC can be isometrically deformed into a spacelike rotational CMC surface, except for the yellow cases.

## Deformations of Lorentzian Surfaces

Let $S_{\gamma}$ be a Lorentzian surface of $\mathbb{L}^{3}$ with timelike profile curve $\gamma$.

## Deformations of Lorentzian Surfaces

Let $S_{\gamma}$ be a Lorentzian surface of $\mathbb{L}^{3}$ with timelike profile curve $\gamma$.Then, we have the following orbits of the isometric deformations

(o) $H=0$

(P) $H \neq 0$

## Deformations of Lorentzian Surfaces

Now, if $\gamma$ is a spacelike profile curve of a Lorentzian surface $S_{\gamma}$ of $\mathbb{L}^{3}$

## Deformations of Lorentzian Surfaces

Now, if $\gamma$ is a spacelike profile curve of a Lorentzian surface $S_{\gamma}$ of $\mathbb{L}^{3}$, the isometric deformations appear in the following diagrams

(s) $H=0$

(T) $H \neq 0$

## References

1. J. Arroyo, O. J. Garay and A. Pámpano, Invariant Surfaces of Constant Mean Curvature, In preparation, 2017.
2. W. Blaschke, Vorlesungen über Differentialgeometrie und geometrische Grundlagen von Einsteins Relativittstheorie I: Elementare Differentialgeometrie, Springer, Berlin, 1930.
3. O. J. Garay and A. Pámpano, Binormal Evolution of Curves with Prescribed Velocity, WSEAS transactions on fluid mechanics 11, 2016, pp. 112-120.
4. O. J. Garay and A. Pámpano, Binormal Motion of Curves with Constant Torsion in 3-Spaces, Preprint, 2017.
5. J. Hano and K. Nomizu, Surfaces of Revolution with Constant Mean Curvature in Lorentz-Minkowski Space, Tohoku Math. Journ., vol. 36 (1984), 427-437.
6. R. López, Timelike Surfaces with Constant Mean Curvature in Lorentz 3-Space, Tohoku Mathematical Journal 52 (2000), no. 4, 515-532.
7. N. Sasahara, Spacelike helicoidal surfaces with constant mean curvature in Minkowski 3-space, Tokyo J. Math., vol. 23 (2000).

## The End



Acknowledgements: This research was supported by by MINECO-FEDER grant MTM2014-54804-P and Gobierno Vasco grant IT1094-16. The author has also been supported by Programa Predoctoral de Formacion de Personal Investigador No Doctor, Gobierno Vasco, 2015.

