

Review for Exam # 2, Math 2450, Fall 2015
Chapter Sections: 11.4-11.8, 12.1-12.5, 12.7-12.8, 13.2

Review: Four Homework Assignments, Webwork 5, 6, 7 and Quizzes # 2,3.

Tangent plane to $z = f(x, y)$ at a point $P_0(x_0, y_0, z_0)$: $\vec{N} = \langle f_x(x_0, y_0), f_y(x_0, y_0), -1 \rangle = \langle A, B, -1 \rangle$ is normal to the surface. Tangent plane is $z - z_0 = A(x - x_0) + B(y - y_0)$.

Tangent plane to an implicit surface $F(x, y, z) = c$ at a point $P_0 = P(x_0, y_0, z_0)$: $\nabla F = \langle F_x, F_y, F_z \rangle|_{P_0} = \langle A, B, C \rangle$ evaluated at P_0 is the normal to the surface, so the tangent plane is $A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$. The line normal to the tangent plane at P_0 : $x = x_0 + At, y = y_0 + Bt, z = z_0 + Ct$.

Incremental Approximation at $P(x_0, y_0)$: $\Delta f = f(x + \Delta x, y + \Delta y) - f(x, y) \approx f_x \Delta x + f_y \Delta y$, where the partials are evaluated at (x_0, y_0) ; Total differential for $f(x, y, z)$: $df = f_x dx + f_y dy + f_z dz$.

Chain rule for $z = f(x, y)$, $x \equiv x(t)$, $y \equiv y(t)$, $z \equiv f(x(t), y(t))$: $\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$. For $z = f(x, y)$, $x \equiv x(u, v)$, $y \equiv y(u, v)$, $z = f(x(u, v), y(u, v))$:

$$\frac{\partial z}{\partial v} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial v}$$

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial u}$$

Implicit differentiation $F(x, y(x)) = c$: $F_x + F_y \frac{dy}{dx} = 0$ which means $\frac{dy}{dx} = -\frac{F_x}{F_y}$.

Gradient of $f(x, y, z)$ is the vector $\nabla f = f_x \vec{i} + f_y \vec{j} + f_z \vec{k}$. The directional derivative $D_{\vec{u}} f = \nabla f \cdot \vec{u}$ is a scalar representing the slope of $f(x, y, z)$ in the direction \vec{u} , where \vec{u} is a unit vector. Maximal property: largest value of the directional derivative $D_{\vec{u}} f$ at the point $P_0(x_0, y_0, z_0)$ occurs in the direction of the gradient, ∇f_0 , and smallest value occurs in the negative direction of the gradient, $-\nabla f_0$. The largest value of the directional derivative at the point P_0 is the magnitude of the gradient $\|\nabla f_0\|$ and smallest value is negative of the magnitude of the gradient $-\|\nabla f_0\|$.

Local extrema of a function of two variables $z = f(x, y)$: find the critical points P_0 in the domain by solving simultaneously the equations $f_x = 0$ and $f_y = 0$ for (x, y) . Test the critical points using the Second partial derivative test where $D = f_{xx}f_{yy} - f_{xy}^2$ is evaluated at a critical point P_0 . There is a *relative maximum* $f(P_0)$ if at P_0 , $D > 0$ and $f_{xx} < 0$, a *relative minimum* if at P_0 , $D > 0$ and $f_{xx} > 0$ and a *saddle point* if at P_0 , $D < 0$. If $D = 0$, test fails.

Absolute extrema of a function of two variables $z = f(x, y)$ on a closed and bounded set S : find the critical points P_0 in S and on the boundary of S , then evaluate the function at these critical points and boundary points. The largest f value is the absolute maximum and the smallest is the absolute minimum.

Lagrange Multipliers is a method to find a maximum or minimum of a function subject to one or more constraints. Maximize or minimize $f(x, y, z)$ subject to $g(x, y, z) = c = \text{constant}$, then solve $f_x = \lambda g_x, f_y = \lambda g_y, f_z = \lambda g_z$ and $g(x, y, z) = c$ for (x, y, z, λ) and check which point gives the largest (or smallest) f value.

Multiple integration over rectangular regions: $R: a \leq x \leq b, c \leq y \leq d$. Fubini's Theorem: If $f(x, y)$ is continuous on R , then the double integral can be written as an iterated integral:

$$\iint_R f(x, y) dA = \int_c^d \int_a^b f(x, y) dx dy = \int_a^b \int_c^d f(x, y) dy dx.$$

Multiple integration over nonrectangular region R : $a \leq x \leq b$ and $g(x) \leq y \leq h(x)$.

$$\iint_R f(x, y) dA = \int_a^b \int_{g(x)}^{h(x)} f(x, y) dy dx$$

Change the order of integration to $dx dy$.

Polar Coordinates (r, θ) : r is the distance in xy plane from the origin, $r \geq 0$, θ is the polar angle measured from the positive x axis counterclockwise, $0 \leq \theta \leq 2\pi$. $x = r \cos(\theta)$, $y = r \sin(\theta)$, $r^2 = x^2 + y^2$, $\tan(\theta) = \frac{y}{x}$, $dA = r dr d\theta$.

$$\iint_R f(x, y) dx dy = \iint_{R^*} f(r \cos(\theta), r \sin(\theta)) r dr d\theta.$$

Surface area of $z = f(x, y)$ inside the region R in a plane: $\iint_R \sqrt{[f_x(x, y)]^2 + [f_y(x, y)]^2 + 1} \, dx \, dy.$

Triple integrals:

$$\iiint_D f(x, y, z) dV = \iiint_D f(x, y, z) \, dx \, dy \, dz.$$

If $f(x, y, z) = 1$, the triple integral is the volume of D . Change order of integration to $dy \, dx \, dz$ or $dz \, dy \, dx$, etc.

Cylindrical Coordinates: Coordinates on a cylinder (r, θ, z) , polar coordinates in x and y but z remains the same.
 $x = r \cos(\theta)$, $y = r \sin(\theta)$, $z = z$, $dV = dz \, r \, dr \, d\theta$.

$$\iiint_D f(x, y, z) \, dx \, dy \, dz = \iiint_{D^*} f(r \cos(\theta), r \sin(\theta), z) \, r \, dz \, dr \, d\theta$$

Spherical Coordinates: Coordinates on a sphere (ρ, θ, ϕ) : ρ is distance from origin, $\rho \geq 0$, θ is polar angle measured in xy plane from the positive x axis counterclockwise, $0 \leq \theta \leq 2\pi$ and ϕ is the angle measured from the north pole (positive z axis) toward the south pole (negative z axis), $0 \leq \phi \leq \pi$.

$x = \rho \sin \phi \cos \theta$, $y = \rho \sin \phi \sin \theta$, $z = \rho \cos \phi$, $\rho^2 = x^2 + y^2 + z^2$, $dV = \rho^2 \sin(\phi) \, d\rho \, d\phi \, d\theta$

$$\iiint_D f(x, y, z) \, dx \, dy \, dz = \iiint_{D^*} f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \, \rho^2 \sin(\phi) \, d\rho \, d\phi \, d\theta.$$

Jacobians: Change of Variables: $x = g(u, v)$ and $y = h(u, v)$. Jacobian determinant:

$$J(u, v) = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial y}{\partial u} \frac{\partial x}{\partial v}$$

$$\iint_D f(x, y) \, dy \, dx = \iint_{D^*} f(g(u, v), h(u, v)) |J(u, v)| \, du \, dv$$

Vector Field: $\vec{F}(x, y, z) = \langle M, N, P \rangle$ $\vec{R}(t) = \langle x(t), y(t), z(t) \rangle$ Use parametric equations for $x(t)$, $y(t)$, and $z(t)$ to define the curve C , $a \leq t \leq b$.

Line integral: $\int_C f(x, y, z) \, ds = \int_a^b f(x(t), y(t), z(t)) \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2} \, dt.$

Line integral: $\int_C [f(x, y) \, dx + g(x, y) \, dy] = \int_a^b [f(x(t), y(t))x'(t) \, dt + g(x(t), y(t))y'(t) \, dt].$

Line integral: $\int_C \vec{F} \cdot d\vec{R} = \int_C [M \, dx + N \, dy + P \, dz].$

Several curves: $C = C_1 \cup C_2 \cup C_3$: $\int_C = \int_{C_1} + \int_{C_2} + \int_{C_3}$.

Review Exercises:

Chapter 11, pp. 910-11 # 29,35,37,43,47,49,51,55,63,65;

Chapter 12, pp. 1010-13 #5,9,17,19,21,23,29,35,37,39,40,42,53,61;

Chapter 13, pp. 1098-99 # 10,23.