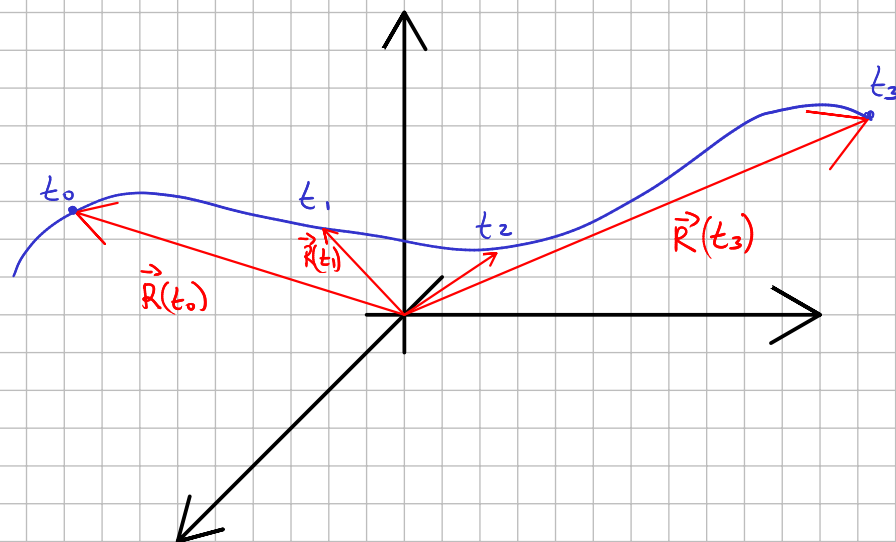


10.1 VECTOR VALUE FUNCTIONS: $\vec{R}(t) = \langle x(t), y(t), z(t) \rangle \quad t \in D$

DEF. A vector value function is a rule that associates for any t in the domain D a unique vector $\vec{R}(t)$ in the range R .

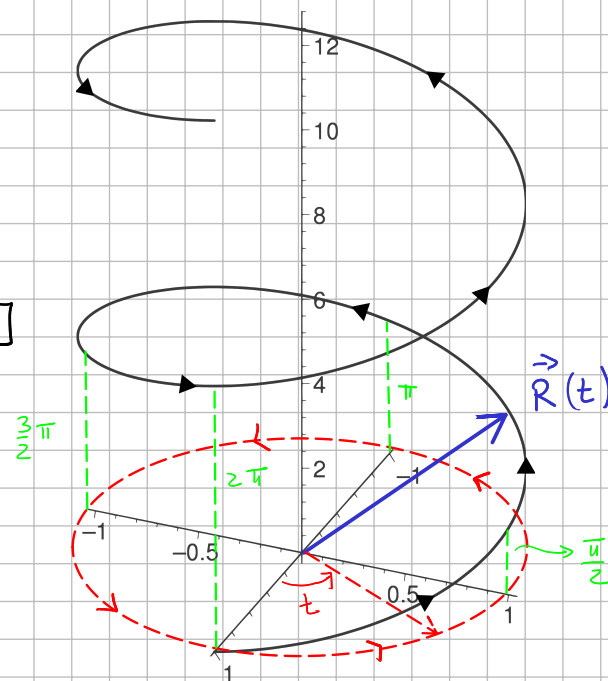


Duality between vector functions and parametric equations

$$\vec{R}(t) = \langle f(t), g(t), h(t) \rangle \quad t \in D$$

$$\begin{cases} x(t) = f(t) \\ y(t) = g(t) \\ z(t) = h(t) \end{cases} \quad \begin{array}{l} \updownarrow \\ \text{Graph described} \\ \text{by the vector} \\ \text{function} \end{array}$$

Ex. Helix $\vec{R}(t) = \langle \cos t, \sin t, t \rangle \quad t \in [0, 4\pi]$



If the domain D is not given we take the largest set for which each component is defined.

Ex. Find the domain of $\vec{R}(t) = \langle \ln t, \frac{1}{t^2-1}, \tan t \rangle$

$D_1: \ln t$ is defined on $t > 0$

$D_2: \frac{1}{t^2-1}$ is defined for $t \neq \pm 1$

$D_3: \tan t$ is defined for $t \neq \frac{\pi}{2} \pm k\pi$, for $k \in \mathbb{N}$

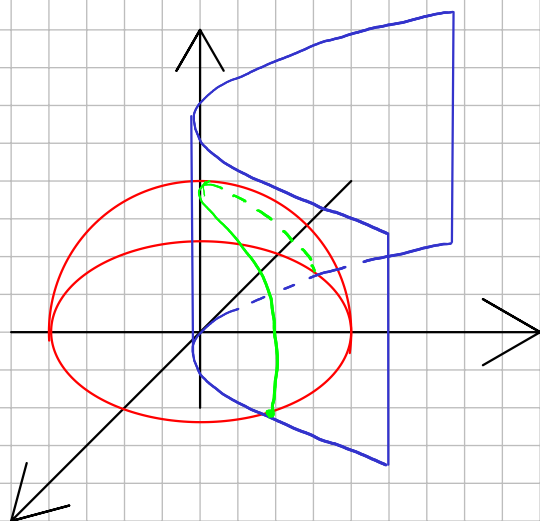
$$D = D_1 \cap D_2 \cap D_3 :$$

$\Rightarrow$

$$\left\{ \underline{t > 0} \setminus \left\{ \underline{t = 1 \cup t = \frac{\pi}{2} + k\pi \text{ for } k \in \mathbb{N}} \right\} \right\}$$

Ex. Find a vector function that describes the intersection between

$$z = \sqrt{4 - x^2 - y^2} \quad \text{and} \quad y = x^2$$



$$\begin{cases} x(t) = t \\ y(t) = x^2(t) = t^2 \\ z(t) = \sqrt{4 - x^2(t) - y^2(t)} = \sqrt{4 - t^2 - t^4} \end{cases}$$

$$\vec{R}(t) = \langle t, t^2, \sqrt{4 - t^2 - t^4} \rangle \quad \text{For } 4 - t^2 - t^4 \geq 0$$

Algebra. We use the same algebra we used for vectors:

DEF.

Let $\vec{F}$ and $\vec{G}$ be vector functions and $F(t)$ be a regular function.

$$(F\vec{F})(t) = F(t) \vec{F}(t)$$

$$(\vec{F} \pm \vec{G})(t) = \vec{F}(t) \pm \vec{G}(t)$$

$$(\vec{F} \cdot \vec{G})(t) = \vec{F}(t) \cdot \vec{G}(t)$$

$$(\vec{F} \times \vec{G})(t) = \vec{F}(t) \times \vec{G}(t)$$

All these operations are defined on the intersection of the domains of the functions that compose the operation.

Ex. $\vec{F}(t) = \langle t^2, t, -\sin t \rangle$ $\vec{G}(t) = \langle t, \frac{1}{t}, 5 \rangle$. Find

$(\vec{F} + \vec{G})(t)$ $(e^t \vec{F})(t)$ $(\vec{F} \cdot \vec{G})(t)$ $(\vec{F} \times \vec{G})(t)$

$$(\vec{F} + \vec{G})(t) = \langle t^2 + t, t + \frac{1}{t}, -\sin t + 5 \rangle \quad D_1 \cap D_2 \text{ for } t \neq 0$$

$$e^t \langle t^2, t, -\sin t \rangle = \langle e^t t^2, e^t t, e^t (-\sin t) \rangle \text{ for all } t \in (-\infty, \infty)$$

$$\underline{(\vec{F} \cdot \vec{G})(t)} = t^2(t) + t\left(\frac{1}{t}\right) + (-\sin t)5 = \underline{t^3 + 1 - 5\sin t} \text{ for } t \neq 0$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ t^2 & t & -\sin t \\ t & \frac{1}{t} & 5 \end{vmatrix} = \hat{i}(5t - (-\sin t)\frac{1}{t}) - \hat{j}(5t^2 - (-\sin t) + \hat{k}(t^2(\frac{1}{t}) - t(t))$$

$$= \left\langle 5t + \frac{\sin t}{t}, -5t^2 - t\sin t, t - t^2 \right\rangle \quad D_1 \cap D_2 : t \neq 0$$

Limit: $\lim_{t \rightarrow t_0} \vec{F}(t) = \lim_{t \rightarrow t_0} \langle F_1(t), F_2(t), F_3(t) \rangle = \langle \lim_{t \rightarrow t_0} F_1(t), \lim_{t \rightarrow t_0} F_2(t), \lim_{t \rightarrow t_0} F_3(t) \rangle$

The limit of the vector function exists if and only if the limit of each component exists.

Ex. Find the $\lim_{t \rightarrow 0} \langle e^t(1+t^2), \frac{1 - \cos t}{t^2}, \frac{3t^4 - 4t^3}{7t^3 - t^2} \rangle = \langle l_1, l_2, l_3 \rangle = \langle 1, 1/2, 0 \rangle$

$$\lim_{t \rightarrow 0} e^t(1+t^2) = l_1 = e^0(1+0^2) = 1(1) = 1$$

$$\lim_{t \rightarrow 0} \frac{1 - \cos(t)}{t^2} = l_2 = \frac{1 - 1}{0^2} = \frac{0}{0} \text{ undeterminate form}$$

l'Hospital's Rule:

$$\lim_{t \rightarrow 0} \frac{\sin t}{2t} = \frac{0}{0} \quad \lim_{t \rightarrow 0} \frac{\cos t}{2} = \frac{1}{2}$$

this answer is wrong, more work is needed

$$\lim_{t \rightarrow 0} \frac{3t^4 - 4t^3}{7t^3 - t^2} = l_3 = \frac{0}{0} = \lim_{t \rightarrow 0} \frac{\cancel{t^3}(3t - 4)}{\cancel{t^3}(7t - 1)} = \frac{0}{-1} = 0$$

Algebra of the limits

THEOREM

$$i) \lim_{t \rightarrow t_0} (\vec{F}(t) \pm \vec{G}(t)) = \lim_{t \rightarrow t_0} \vec{F}(t) \pm \lim_{t \rightarrow t_0} \vec{G}(t)$$

$$ii) \lim_{t \rightarrow t_0} (g(t) \vec{F}(t)) = \lim_{t \rightarrow t_0} g(t) \cdot \lim_{t \rightarrow t_0} \vec{F}(t)$$

$$iii) \lim_{t \rightarrow t_0} \vec{F}(t) \cdot \vec{G}(t) = \lim_{t \rightarrow t_0} \vec{F}(t) \cdot \lim_{t \rightarrow t_0} \vec{G}(t)$$

$$iv) \lim_{t \rightarrow t_0} \vec{F}(t) \times \vec{G}(t) = \lim_{t \rightarrow t_0} \vec{F}(t) \times \lim_{t \rightarrow t_0} \vec{G}(t)$$

Proof iii) (for the dot product)

$$\begin{aligned} \lim_{t \rightarrow t_0} (\vec{F}(t) \cdot \vec{G}(t)) &= \lim_{t \rightarrow t_0} (f_1 g_1 + f_2 g_2 + f_3 g_3)(t) = \lim_{t \rightarrow t_0} f_1 \lim_{t \rightarrow t_0} g_1 + \lim_{t \rightarrow t_0} f_2 \lim_{t \rightarrow t_0} g_2 + \lim_{t \rightarrow t_0} f_3 \lim_{t \rightarrow t_0} g_3 \\ &= \left\langle \lim_{t \rightarrow t_0} f_1, \lim_{t \rightarrow t_0} f_2, \lim_{t \rightarrow t_0} f_3 \right\rangle \cdot \left\langle \lim_{t \rightarrow t_0} g_1, \lim_{t \rightarrow t_0} g_2, \lim_{t \rightarrow t_0} g_3 \right\rangle \end{aligned}$$

$$= \lim_{t \rightarrow t_0} \vec{F}(t) \cdot \lim_{t \rightarrow t_0} \vec{G}(t)$$

show that $\lim_{t \rightarrow 1} \vec{F}(t) \times \vec{G}(t) = \lim_{t \rightarrow 1} \vec{F}(t) \times \lim_{t \rightarrow 1} \vec{G}(t)$ with

$$\vec{F}(t) = \langle t, 1-t, t^2 \rangle$$

$$\vec{G}(t) = \langle e^t, 0, -2-e^t \rangle$$

$$h_1 = \langle 1, 0, 1 \rangle$$

$$h_2 = \langle e^1, 0, -2-e^1 \rangle = \langle e, 0, -2-e \rangle$$

$$\vec{F} \times \vec{G} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ t & 1-t & t^2 \\ e^t & 0 & -2-e^t \end{vmatrix} = \hat{i}((1-t) - (-2-e^t)) - \hat{j}(t(-2-e^t) - t^2 e^t) + \hat{k}(0 - (1-t)e^t)$$

$$\lim_{t \rightarrow 1} \vec{F} \times \vec{G} = \langle 0, -(-2-e-e), 0 \rangle = \langle 0, 2+2e, 0 \rangle$$

Alternatively, you could use this strategy:

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & 1 \\ e & 0 & -2-e \end{vmatrix} = \hat{i}(0) - \hat{j}((-2-e)-e) + \hat{k}(0) = \langle 0, 2+2e, 0 \rangle$$

Def. A vector function $\vec{F}$ is continuous at t_0 if t_0 is in the domain of $\vec{F}$ and $\lim_{t \rightarrow t_0} \vec{F}(t) = \vec{F}(t_0)$

A vector function is continuous at t_0 if and only if each component is continuous at t_0 .

Ex. Find where the function $\vec{F} = \langle \sin t, (1-t)^{-1}, \ln t \rangle$ is continuous.

$\sin(t)$ D_1 : for t

$\frac{1}{1-t}$ D_2 $t \neq 1$

$\ln t$ D_3 $t > 0$

"set minus"

$$D_1 \cap D_2 \cap D_3 = \{t > 0 \setminus t = 1\}$$

↪ Is equivalent to:

$$\{t > 0 \text{ with } t \neq 1\}$$