On the Stokes and Laplacian operators in Navier–Stokes equations

Luan Thach Hoang

School of Mathematics, University of Minnesota

Nov. 27, 2006 Dynamical System and PDE Seminars, School of Mathematics University of Minnesota, Twin Cities



Introduction

◆□ → ◆圖 → ◆ 国 → ▲ 国 → 今へ⊙

Introduction

Main results



Introduction

Main results

Proofs of Main Results



Introduction

Main results

Proofs of Main Results

Spherical Domain



Introduction

Main results

Proofs of Main Results

Spherical Domain

Estimates in Navier-Stokes equations

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Introduction

Main results

Proofs of Main Results

Spherical Domain

Estimates in Navier-Stokes equations

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Other discussions

Let Ω be an open, bounded subset of $\mathbb{R}^3.$ The Navier–Stokes equations in $\Omega:$

$$\partial_t u - \nu \Delta u + (u \cdot \nabla)u + \nabla p = f,$$

 $\nabla \cdot u = 0.$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Let Ω be an open, bounded subset of \mathbb{R}^3 . The Navier–Stokes equations in Ω :

$$\partial_t u - \nu \Delta u + (u \cdot \nabla)u + \nabla p = f,$$

 $\nabla \cdot u = 0.$

Boundary conditions: Dirichlet condition, or periodic condition, or slip+Neumann conditions, or

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Let Ω be an open, bounded subset of \mathbb{R}^3 . The Navier–Stokes equations in Ω :

$$\partial_t u - \nu \Delta u + (u \cdot \nabla)u + \nabla p = f,$$

 $\nabla \cdot u = 0.$

Boundary conditions: Dirichlet condition, or periodic condition, or slip+Neumann conditions, or Navier boundary condtion:

$$u \cdot N = 0$$
, $\nu[(Du)N]_{tan} = 0$, on $\partial \Omega$,

where N is the unit outward normal vector to the boundary, $[\cdot]_{tan}$ means the tangential part.

Let Ω be an open, bounded subset of $\mathbb{R}^3.$ The Navier–Stokes equations in $\Omega:$

$$\partial_t u - \nu \Delta u + (u \cdot \nabla)u + \nabla p = f,$$

 $\nabla \cdot u = 0.$

Boundary conditions: Dirichlet condition, or periodic condition, or slip+Neumann conditions, or Navier boundary condtion:

$$u \cdot N = 0$$
, $\nu[(Du)N]_{tan} = 0$, on $\partial \Omega$,

where N is the unit outward normal vector to the boundary, $[\cdot]_{tan}$ means the tangential part.

Assume $\nu = 1$.

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection. $Au = -\Delta u$ for $u \in D_A$ in some cases such as

Periodic domains

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

 $Au = -\Delta u$ for $u \in D_A$ in some cases such as

- Periodic domains
- Rectangular domains with u satisfying periodic conditon on the sides and Navier condition on the top and bottom.

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

 $Au = -\Delta u$ for $u \in D_A$ in some cases such as

- Periodic domains
- Rectangular domains with u satisfying periodic conditon on the sides and Navier condition on the top and bottom.

In the case $Au \neq -\Delta u$, what is the estimate for $||Au + \Delta u||_{L^2}$?

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

 $Au = -\Delta u$ for $u \in D_A$ in some cases such as

- Periodic domains
- Rectangular domains with u satisfying periodic conditon on the sides and Navier condition on the top and bottom.

In the case $Au \neq -\Delta u$, what is the estimate for $||Au + \Delta u||_{L^2}$? Obviously, $||Au + \Delta u||_{L^2} \leq C ||u||_{H^2}$.

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

 $Au = -\Delta u$ for $u \in D_A$ in some cases such as

- Periodic domains
- Rectangular domains with u satisfying periodic conditon on the sides and Navier condition on the top and bottom.

In the case $Au \neq -\Delta u$, what is the estimate for $||Au + \Delta u||_{L^2}$? Obviously, $||Au + \Delta u||_{L^2} \leq C ||u||_{H^2}$.

What is C or Can we replace H^2 -norm by H^1 -norm?

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

 $Au = -\Delta u$ for $u \in D_A$ in some cases such as

- Periodic domains
- Rectangular domains with u satisfying periodic conditon on the sides and Navier condition on the top and bottom.

In the case $Au \neq -\Delta u$, what is the estimate for $||Au + \Delta u||_{L^2}$? Obviously, $||Au + \Delta u||_{L^2} \leq C ||u||_{H^2}$. What is *C* or Can we replace H^2 -norm by H^1 -norm? For thin domains: Chueshov-Raugel-Rekalo (2-layer thin domain), Iftimie-Raugel-Sell (thin domain with flat bottom+Navier condition):

$$\|Au+\Delta u\|_{L^2}\leq C\varepsilon\|u\|_{H^2}+C\|u\|_{H^1}.$$

Usual Stokes operator: $Au = P(-\Delta u)$ for $u \in D_A$, domain of A, where P is the Leray projection.

 $Au = -\Delta u$ for $u \in D_A$ in some cases such as

- Periodic domains
- Rectangular domains with u satisfying periodic conditon on the sides and Navier condition on the top and bottom.

In the case $Au \neq -\Delta u$, what is the estimate for $||Au + \Delta u||_{L^2}$? Obviously, $||Au + \Delta u||_{L^2} \leq C ||u||_{H^2}$. What is *C* or Can we replace H^2 -norm by H^1 -norm? For thin domains: Chueshov-Raugel-Rekalo (2-layer thin domain), Iftimie-Raugel-Sell (thin domain with flat bottom+Navier condition):

$$\|Au+\Delta u\|_{L^2}\leq C\varepsilon\|u\|_{H^2}+C\|u\|_{H^1}.$$

Can we improve this?

Consider an open, bounded, connected domain $\Omega \subset \mathbb{R}^3$ with C^3 boundary satisfying: **Condition (B).** For $a, b \in \mathbb{R}^3$, if $(a + b \times x) \cdot N = 0$ on $\partial\Omega$, then b = 0.

Consider an open, bounded, connected domain $\Omega \subset \mathbb{R}^3$ with C^3 boundary satisfying: **Condition (B).** For $a, b \in \mathbb{R}^3$, if $(a + b \times x) \cdot N = 0$ on $\partial\Omega$, then b = 0.

Let $\tilde{H} = \{ u \in L^2(\Omega, \mathbb{R}^3) : \nabla \cdot u = 0 \text{ in } \Omega \text{ and } u \cdot N = 0 \text{ on } \partial \Omega \}.$ We have the Helmholtz-Leray decomposition

$$L^2(\Omega, \mathbb{R}^3) = \tilde{H} \oplus \tilde{H}^{\perp}$$
 where $\tilde{H}^{\perp} = \{ \nabla \phi : \phi \in H^1(\Omega) \}.$

Consider an open, bounded, connected domain $\Omega \subset \mathbb{R}^3$ with C^3 boundary satisfying: **Condition (B).** For $a, b \in \mathbb{R}^3$, if $(a + b \times x) \cdot N = 0$ on $\partial\Omega$, then b = 0. Let $\tilde{H} = \{u \in L^2(\Omega, \mathbb{R}^3) : \nabla \cdot u = 0 \text{ in } \Omega \text{ and } u \cdot N = 0 \text{ on } \partial\Omega\}$. We have the Helmholtz-Leray decomposition

$$L^2(\Omega, \mathbb{R}^3) = \tilde{H} \oplus \tilde{H}^{\perp}$$
 where $\tilde{H}^{\perp} = \{ \nabla \phi : \phi \in H^1(\Omega) \}.$

The projection \tilde{P} from $L^2(\Omega, \mathbb{R}^3)$ onto \tilde{H} is standard in the study of Navier–Stokes equations.

Consider an open, bounded, connected domain $\Omega \subset \mathbb{R}^3$ with C^3 boundary satisfying: **Condition (B).** For $a, b \in \mathbb{R}^3$, if $(a + b \times x) \cdot N = 0$ on $\partial\Omega$, then b = 0. Let $\tilde{H} = \{u \in L^2(\Omega, \mathbb{R}^3) : \nabla \cdot u = 0 \text{ in } \Omega \text{ and } u \cdot N = 0 \text{ on } \partial\Omega\}$. We have the Helmholtz-Leray decomposition

$$L^2(\Omega, \mathbb{R}^3) = \tilde{H} \oplus \tilde{H}^{\perp}$$
 where $\tilde{H}^{\perp} = \{ \nabla \phi : \phi \in H^1(\Omega) \}.$

The projection \tilde{P} from $L^2(\Omega, \mathbb{R}^3)$ onto \tilde{H} is standard in the study of Navier–Stokes equations.

However, in the case of Navier boundary condition, we consider

$$ilde{H}=H\oplus H_0$$
 where $H_0=\{u\in ilde{H}: u=a+b{ imes}x, ext{ for some } a,b\in \mathbb{R}^3\}.$

Consider an open, bounded, connected domain $\Omega \subset \mathbb{R}^3$ with C^3 boundary satisfying: **Condition (B).** For $a, b \in \mathbb{R}^3$, if $(a + b \times x) \cdot N = 0$ on $\partial\Omega$, then b = 0. Let $\tilde{H} = \{u \in L^2(\Omega, \mathbb{R}^3) : \nabla \cdot u = 0 \text{ in } \Omega \text{ and } u \cdot N = 0 \text{ on } \partial\Omega\}$. We have the Helmholtz-Leray decomposition

$$L^2(\Omega, \mathbb{R}^3) = \tilde{H} \oplus \tilde{H}^{\perp}$$
 where $\tilde{H}^{\perp} = \{ \nabla \phi : \phi \in H^1(\Omega) \}.$

The projection \tilde{P} from $L^2(\Omega, \mathbb{R}^3)$ onto \tilde{H} is standard in the study of Navier–Stokes equations.

However, in the case of Navier boundary condition, we consider

$$ilde{H} = H \oplus H_0$$
 where $H_0 = \{ u \in ilde{H} : u = a + b imes x, ext{ for some } a, b \in \mathbb{R}^3 \}.$

The subspace H_0 arises from the variational formulation of Navier–Stokes equations with Navier boundary condition.

The Leray projection P is defined to be the orthogonal projection from $L^2(\Omega, \mathbb{R}^3)$ onto H.

The Leray projection P is defined to be the orthogonal projection from $L^2(\Omega, \mathbb{R}^3)$ onto H. The Stokes operator is

$$Au = P(-\Delta u), \quad u \in D_A,$$

where the domain D_A is

 $D_A = \{ u \in H^2(\Omega, \mathbb{R}^3) \cap H, u \text{ satisfies Navier boundary condition on } \partial \Omega \}.$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

The Leray projection P is defined to be the orthogonal projection from $L^2(\Omega, \mathbb{R}^3)$ onto H. The Stokes operator is

$$Au = P(-\Delta u), \quad u \in D_A,$$

where the domain D_A is

 $D_A = \{ u \in H^2(\Omega, \mathbb{R}^3) \cap H, u \text{ satisfies Navier boundary condition on } \partial \Omega \}.$

Condition (B) implies $H_0 = \{0\}$ and $P = \tilde{P}$.

Consider three dimensional thin domains of the form

$$\begin{split} \Omega_{\varepsilon}' &= \{(x_1, x_2, x_3) : (x_1, x_2) \in \mathbb{R}^2, \varepsilon g_0(x_1, x_2) < x_3 < \varepsilon g_1(x_1, x_2)\}, \\ \text{where } \varepsilon \in (0, 1], \ g_0 \text{ and } g_1 \text{ are given } C^3 \text{ scalar functions in } \mathbb{R}^2 \\ \text{satisfying} \end{split}$$

$$g_i(x'+{f e}_j)=g_i(x'), \quad x'\in {\mathbb R}^2, \,\, i=0,1, \,\, j=1,2,$$

where $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ is the standard basis of \mathbb{R}^3 . We assume that

$$g=g_1-g_0\geq \alpha>0.$$

Consider three dimensional thin domains of the form

 $\Omega_{\varepsilon}' = \{(x_1, x_2, x_3) : (x_1, x_2) \in \mathbb{R}^2, \varepsilon g_0(x_1, x_2) < x_3 < \varepsilon g_1(x_1, x_2)\},\$ where $\varepsilon \in (0, 1]$, g_0 and g_1 are given C^3 scalar functions in \mathbb{R}^2 satisfying

$$g_i(x'+{f e}_j)=g_i(x'), \quad x'\in {\mathbb R}^2, \,\, i=0,1, \,\, j=1,2,$$

where $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ is the standard basis of \mathbb{R}^3 . We assume that

$$g=g_1-g_0\geq \alpha>0.$$

(日) (同) (三) (三) (三) (○) (○)

 $\partial \Omega'_{\varepsilon} = \Gamma' = (\text{bottom } \Gamma'_0) \cup (\text{top } \Gamma'_1).$

Consider three dimensional thin domains of the form

 $\Omega_{\varepsilon}' = \{(x_1, x_2, x_3) : (x_1, x_2) \in \mathbb{R}^2, \varepsilon g_0(x_1, x_2) < x_3 < \varepsilon g_1(x_1, x_2)\},\$ where $\varepsilon \in (0, 1]$, g_0 and g_1 are given C^3 scalar functions in \mathbb{R}^2 satisfying

$$g_i(x'+{f e}_j)=g_i(x'), \ \ \ x'\in {\mathbb R}^2, \ i=0,1, \ j=1,2,$$

where $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ is the standard basis of \mathbb{R}^3 . We assume that

$$g=g_1-g_0\geq \alpha>0.$$

 $\partial \Omega'_{\varepsilon} = \Gamma' = (\text{bottom } \Gamma'_0) \cup (\text{top } \Gamma'_1).$ One of the representing domains of Ω'_{ε} is

$$\Omega_{\varepsilon} = \{ (x', x_3) : x' \in (0, 1)^2, \varepsilon g_0(x') < x_3 < \varepsilon g_1(x') \}.$$

Consider three dimensional thin domains of the form

$$\begin{split} \Omega_{\varepsilon}' &= \{(x_1, x_2, x_3) : (x_1, x_2) \in \mathbb{R}^2, \varepsilon g_0(x_1, x_2) < x_3 < \varepsilon g_1(x_1, x_2)\}, \\ \text{where } \varepsilon \in (0, 1], \ g_0 \text{ and } g_1 \text{ are given } C^3 \text{ scalar functions in } \mathbb{R}^2 \\ \text{satisfying} \end{split}$$

$$g_i(x'+{f e}_j)=g_i(x'), \ \ \ x'\in {\mathbb R}^2, \ i=0,1, \ j=1,2,$$

where $\{e_1, e_2, e_3\}$ is the standard basis of \mathbb{R}^3 . We assume that

$$g=g_1-g_0\geq\alpha>0.$$

 $\partial \Omega'_{\varepsilon} = \Gamma' = (\text{bottom } \Gamma'_0) \cup (\text{top } \Gamma'_1).$ One of the representing domains of Ω'_{ε} is

$$\Omega_{arepsilon} = \{(x',x_3): x'\in (0,1)^2, arepsilon g_0(x') < x_3 < arepsilon g_1(x')\}.$$

We study the divergence-free vector fields u(x) in Ω'_{ε} that satisfy the periodicity condition

$$u(x + \mathbf{e}_j) = u(x)$$
 for all $x \in \Omega'_{\varepsilon}$, $j = 1, 2$,

▲□▶ ▲□▶ ▲□▶ ▲□▶ □□ − のへで

and the Navier boundary condition on Γ' .

Let $L^2_{\text{per}}(\Omega'_{\varepsilon})$, resp. $H^k_{\text{per}}(\Omega'_{\varepsilon}), k \ge 1$, be the closure with respect to the norm $\|\cdot\|_{L^2(\Omega_{\varepsilon})}$, resp. $\|\cdot\|_{H^k(\Omega_{\varepsilon})}$, of the set of all functions $\varphi \in C^{\infty}(\overline{\Omega'_{\varepsilon}})$ satisfying

$$\varphi(x + \mathbf{e}_j) = \varphi(x)$$
 for all $x \in \Omega'_{\varepsilon}, \ j = 1, 2$.

Let $L^2_{\text{per}}(\Omega'_{\varepsilon})$, resp. $H^k_{\text{per}}(\Omega'_{\varepsilon}), k \ge 1$, be the closure with respect to the norm $\|\cdot\|_{L^2(\Omega_{\varepsilon})}$, resp. $\|\cdot\|_{H^k(\Omega_{\varepsilon})}$, of the set of all functions $\varphi \in C^{\infty}(\overline{\Omega'_{\varepsilon}})$ satisfying

$$arphi(x+\mathbf{e}_j)=arphi(x)$$
 for all $x\in \Omega'_arepsilon,\ j=1,2.$

We define

$$H_0 = \{ u = a + b \times x \in L^2_{\operatorname{per}}(\Omega'_{\varepsilon}, \mathbb{R}^3), u \cdot N = 0 \text{ on } \Gamma', \text{ where } a, b \in \mathbb{R}^3 \}.$$

Let $L^2_{\text{per}}(\Omega'_{\varepsilon})$, resp. $H^k_{\text{per}}(\Omega'_{\varepsilon}), k \ge 1$, be the closure with respect to the norm $\|\cdot\|_{L^2(\Omega_{\varepsilon})}$, resp. $\|\cdot\|_{H^k(\Omega_{\varepsilon})}$, of the set of all functions $\varphi \in C^{\infty}(\overline{\Omega'_{\varepsilon}})$ satisfying

$$\varphi(x + \mathbf{e}_j) = \varphi(x)$$
 for all $x \in \Omega'_{\varepsilon}, \ j = 1, 2$.

We define

$$H_0 = \{ u = a + b \times x \in L^2_{\operatorname{per}}(\Omega'_{\varepsilon}, \mathbb{R}^3), u \cdot N = 0 \text{ on } \Gamma', \text{ where } a, b \in \mathbb{R}^3 \}.$$

Let $u = a + b \times x \in H_0$, where $a, b \in \mathbb{R}^3$. The periodicity condition implies b = 0. Hence Condition (B) is satisfied and therefore $H_0 = \{0\}$.

Let $L^2_{per}(\Omega'_{\varepsilon})$, resp. $H^k_{per}(\Omega'_{\varepsilon})$, $k \ge 1$, be the closure with respect to the norm $\|\cdot\|_{L^2(\Omega_{\varepsilon})}$, resp. $\|\cdot\|_{H^k(\Omega_{\varepsilon})}$, of the set of all functions $\varphi \in C^{\infty}(\overline{\Omega'_{\varepsilon}})$ satisfying

$$\varphi(x + \mathbf{e}_j) = \varphi(x)$$
 for all $x \in \Omega'_{\varepsilon}, \ j = 1, 2$.

We define

$$H_0 = \{ u = a + b \times x \in L^2_{\operatorname{per}}(\Omega'_{\varepsilon}, \mathbb{R}^3), u \cdot N = 0 \text{ on } \Gamma', \text{ where } a, b \in \mathbb{R}^3 \}.$$

Let $u = a + b \times x \in H_0$, where $a, b \in \mathbb{R}^3$. The periodicity condition implies b = 0. Hence Condition (B) is satisfied and therefore $H_0 = \{0\}$.

The functional spaces and the Stokes operator are defined as usual (with the periodicity condition).

Main reults

Theorem (General Domain) Let $u \in D_A$, then

$$\|Au+\Delta u\|_{L^2(\Omega)}\leq C\|u\|_{H^1(\Omega)},$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

where C is a positive constant depending on the domain.
Main reults

Theorem (General Domain) Let $u \in D_A$, then

$$\|Au+\Delta u\|_{L^2(\Omega)}\leq C\|u\|_{H^1(\Omega)},$$

where C is a positive constant depending on the domain. Theorem (Thin Domain) Let $u \in D_A$, then

$$\|Au + \Delta u\|_{L^{2}(\Omega_{\varepsilon})} \leq C\varepsilon \|\nabla u\|_{L^{2}(\Omega_{\varepsilon})} + C\|u\|_{L^{2}(\Omega_{\varepsilon})},$$

where the positive constant C is independent of ε .

Lemma (V. Busuioc – T. S. Ratiu)

Let \mathcal{O} be an open subset of \mathbb{R}^3 such that $\Gamma_* = \partial \Omega \cap \mathcal{O} \neq \emptyset$. Let u belong to $C^1(\overline{\Omega} \cap \mathcal{O}, \mathbb{R}^3)$ and satisfy Navier boundary condition on Γ_* . Suppose $\check{N} \in C^1(\overline{\Omega} \cap \mathcal{O}, \mathbb{R}^3)$ with the restriction $\check{N}|_{\Gamma_*}$ being a unit normal vector field on Γ_* . Then

$$\check{N} imes (
abla imes u) = 2\check{N} imes (\check{N} imes ((
abla \check{N})^* u))$$
 on $\Gamma_*.$

Let $\omega = \nabla \times u$. From the identity $\check{N} \times \nabla (u \cdot \check{N}) = 0$ on Γ_* , we have

$$0 = \check{N} \times [(\nabla u)^* \check{N}] + \check{N} \times [(\nabla \check{N})^* u]$$

= $\check{N} \times [(Du)\check{N} - (Ku)\check{N}] + \check{N} \times [(\nabla \check{N})^* u],$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

where $Ku = \frac{\nabla u - (\nabla u)^*}{2}$.

Let $\omega = \nabla \times u$. From the identity $\check{N} \times \nabla (u \cdot \check{N}) = 0$ on Γ_* , we have

$$0 = \check{N} \times [(\nabla u)^* \check{N}] + \check{N} \times [(\nabla \check{N})^* u]$$

= $\check{N} \times [(Du)\check{N} - (Ku)\check{N}] + \check{N} \times [(\nabla \check{N})^* u],$

where $Ku = \frac{\nabla u - (\nabla u)^*}{2}$. Since $(Du)\check{N}$ is co-linear to \check{N} , we thus have

 $\check{N} \times [(\nabla \check{N})^* u] = \check{N} \times [(\kappa u)\check{N}] = \check{N} \times [(1/2)\omega \times \check{N}].$

Let $\omega = \nabla \times u$. From the identity $\check{N} \times \nabla (u \cdot \check{N}) = 0$ on Γ_* , we have

$$0 = \check{N} \times [(\nabla u)^* \check{N}] + \check{N} \times [(\nabla \check{N})^* u]$$

= $\check{N} \times [(Du)\check{N} - (Ku)\check{N}] + \check{N} \times [(\nabla \check{N})^* u],$

where $Ku = \frac{\nabla u - (\nabla u)^*}{2}$. Since $(Du)\check{N}$ is co-linear to \check{N} , we thus have

 $\check{N} \times [(\nabla \check{N})^* u] = \check{N} \times [(\kappa u)\check{N}] = \check{N} \times [(1/2)\omega \times \check{N}].$

Therefore $\check{N} \times (\omega \times \check{N}) = 2\check{N} \times [(\nabla \check{N})^* u].$

Let $\omega = \nabla \times u$. From the identity $\check{N} \times \nabla (u \cdot \check{N}) = 0$ on Γ_* , we have

$$0 = \check{N} \times [(\nabla u)^* \check{N}] + \check{N} \times [(\nabla \check{N})^* u]$$

= $\check{N} \times [(Du)\check{N} - (Ku)\check{N}] + \check{N} \times [(\nabla \check{N})^* u],$

where $Ku = \frac{\nabla u - (\nabla u)^*}{2}$. Since $(Du)\check{N}$ is co-linear to \check{N} , we thus have

$$\check{N} \times [(\nabla \check{N})^* u] = \check{N} \times [(\kappa u)\check{N}] = \check{N} \times [(1/2)\omega \times \check{N}].$$

Therefore $\check{N} \times (\omega \times \check{N}) = 2\check{N} \times [(\nabla \check{N})^* u].$ Then use the identity

$$a \times (a \times (a \times b))) = -|a|^2(a \times b).$$

Lemma (Key Lemma) Let $u \in D_A$ and $\Phi \in H^{\perp}$. Then $\left| \int \Delta u \cdot \Phi dx \right| < C \|\Phi\|_{L^2(\Omega)} \|$

$$\left|\int_{\Omega} \Delta u \cdot \Phi dx\right| \leq C \|\Phi\|_{L^{2}(\Omega)} \|u\|_{H^{1}(\Omega)},$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

where C > 0 depends on Ω .

Let $\omega = \nabla \times u$ and $\Phi = \nabla \phi$. By the density argument, we can assume u and Φ are smooth.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへぐ

Let $\omega = \nabla \times u$ and $\Phi = \nabla \phi$. By the density argument, we can assume u and Φ are smooth. We have $\nabla \times \omega = -\Delta u$ and $\nabla \times \Phi = 0$.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Let $\omega = \nabla \times u$ and $\Phi = \nabla \phi$. By the density argument, we can assume u and Φ are smooth. We have $\nabla \times \omega = -\Delta u$ and $\nabla \times \Phi = 0$. Then

$$\begin{split} \int_{\Omega} \Delta u \cdot \Phi dx &= -\int_{\Omega} (\nabla \times \omega) \cdot \Phi dx \\ &= -\int_{\Omega} \omega \cdot (\nabla \times \Phi) dx - \int_{\partial \Omega} (\omega \times \Phi) \cdot N d\sigma \\ &= \int_{\partial \Omega} (\omega \times N) \cdot \Phi d\sigma. \end{split}$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

Let $\omega = \nabla \times u$ and $\Phi = \nabla \phi$. By the density argument, we can assume u and Φ are smooth. We have $\nabla \times \omega = -\Delta u$ and $\nabla \times \Phi = 0$. Then

$$\begin{split} \int_{\Omega} \Delta u \cdot \Phi dx &= -\int_{\Omega} (\nabla \times \omega) \cdot \Phi dx \\ &= -\int_{\Omega} \omega \cdot (\nabla \times \Phi) dx - \int_{\partial \Omega} (\omega \times \Phi) \cdot N d\sigma \\ &= \int_{\partial \Omega} (\omega \times N) \cdot \Phi d\sigma. \end{split}$$

Let $N(x), x \in \Omega$, be a C^2 -extension of N. Define $G(u) = N \times [(\nabla N)^* u]$ on $\overline{\Omega}$.

Let $\omega = \nabla \times u$ and $\Phi = \nabla \phi$. By the density argument, we can assume u and Φ are smooth. We have $\nabla \times \omega = -\Delta u$ and $\nabla \times \Phi = 0$. Then

$$\int_{\Omega} \Delta u \cdot \Phi dx = -\int_{\Omega} (\nabla \times \omega) \cdot \Phi dx$$
$$= -\int_{\Omega} \omega \cdot (\nabla \times \Phi) dx - \int_{\partial \Omega} (\omega \times \Phi) \cdot N d\sigma$$
$$= \int_{\partial \Omega} (\omega \times N) \cdot \Phi d\sigma.$$

Let $N(x), x \in \Omega$, be a C^2 -extension of N. Define $G(u) = N \times [(\nabla N)^* u]$ on $\overline{\Omega}$. By Busuioc-Ratiu Lemma, we have

$$2N \times G(u)\big|_{\partial\Omega} = N \times \omega.$$

(continued).

We thus have

$$\begin{split} \int_{\Omega} \Delta u \cdot \Phi dx &= -\int_{\partial \Omega} 2(N \times G(u)) \cdot \Phi d\sigma \\ &= \int_{\partial \Omega} 2(\Phi \times G(u)) \cdot N d\sigma \\ &= 2 \int_{\Omega} \nabla \cdot (\Phi \times G(u)) dx \\ &= 2 \int_{\Omega} \Phi \cdot (\nabla \times G(u)) - (\nabla \times \Phi) \cdot G(u) dx \\ &= 2 \int_{\Omega} \Phi \cdot (\nabla \times G(u)) dx. \end{split}$$

(continued).

We thus have

$$\int_{\Omega} \Delta u \cdot \Phi dx = -\int_{\partial \Omega} 2(N \times G(u)) \cdot \Phi d\sigma$$

= $\int_{\partial \Omega} 2(\Phi \times G(u)) \cdot N d\sigma$
= $2 \int_{\Omega} \nabla \cdot (\Phi \times G(u)) dx$
= $2 \int_{\Omega} \Phi \cdot (\nabla \times G(u)) - (\nabla \times \Phi) \cdot G(u) dx$
= $2 \int_{\Omega} \Phi \cdot (\nabla \times G(u)) dx.$

Since $|
abla imes {\it G}(u)| \le {\it C}(|
abla u|+|u|)$, we obtain

$$\left|\int_{\Omega} \Delta u \cdot \Phi dx\right| \leq C \int_{\Omega} |\Phi| (|\nabla u| + |u|) dx \leq C \|\Phi\|_{L^2} \|u\|_{H^1}.$$

Proof of the Inequality in General Domain.

Let $\Phi = Au + \Delta u = -P\Delta u + \Delta u$, then $\Phi \in H^{\perp}$. Since Au and Φ are orthogonal in $L^{2}(\Omega, \mathbb{R}^{3})$, we have

$$\int_{\Omega} |\Phi|^2 dx = \int_{\Omega} (Au + \Delta u) \cdot \Phi dx = \int_{\Omega} \Delta u \cdot \Phi dx.$$

Applying the Key Lemma, we obtain

$$\|\Phi\|_{L^2}^2 \leq C \|\Phi\|_{L^2} \|u\|_{H^1}.$$

<□ > < @ > < E > < E > E のQ @

Key point (from IRS which works for our domain as well): new G(u) defined on $\overline{\Omega_{\varepsilon}}$ which gives a better estimate for $|\nabla \times G(u)|$.

Key point (from IRS which works for our domain as well): new G(u) defined on $\overline{\Omega_{\varepsilon}}$ which gives a better estimate for $|\nabla \times G(u)|$. Note: in Busuioc-Ratiu Lemma, if $\check{N}|_{\Gamma_{\varepsilon}} = \pm N$ then we have

$$N \times (\nabla \times u) = 2N \times (\check{N} \times ((\nabla \check{N})^* u)) \text{ on } \Gamma_*.$$

Key point (from IRS which works for our domain as well): new G(u) defined on $\overline{\Omega_{\varepsilon}}$ which gives a better estimate for $|\nabla \times G(u)|$. Note: in Busuioc-Ratiu Lemma, if $\check{N}|_{\Gamma_*} = \pm N$ then we have

$$N \times (\nabla \times u) = 2N \times (\check{N} \times ((\nabla \check{N})^* u))$$
 on Γ_* .

Find good \tilde{N} defined on $\overline{\Omega'_{\varepsilon}}$ such that

$$\tilde{N}\big|_{\Gamma_0'} = -N$$
 and $\tilde{N}\big|_{\Gamma_1'} = N$.

Key point (from IRS which works for our domain as well): new G(u) defined on $\overline{\Omega_{\varepsilon}}$ which gives a better estimate for $|\nabla \times G(u)|$. Note: in Busuioc-Ratiu Lemma, if $\check{N}|_{\Gamma_*} = \pm N$ then we have

$$N \times (\nabla \times u) = 2N \times (\check{N} \times ((\nabla \check{N})^* u))$$
 on Γ_* .

Find good \tilde{N} defined on $\overline{\Omega'_{\varepsilon}}$ such that

$$\tilde{N}\big|_{\Gamma_0'} = -N$$
 and $\tilde{N}\big|_{\Gamma_1'} = N$.

Define G(u) on the closure of Ω'_{ε} by

$$G(u) = \tilde{N} \times [(\nabla \tilde{N})^* u].$$

(日) (同) (三) (三) (三) (○) (○)

Key point (from IRS which works for our domain as well): new G(u) defined on $\overline{\Omega_{\varepsilon}}$ which gives a better estimate for $|\nabla \times G(u)|$. Note: in Busuioc-Ratiu Lemma, if $\check{N}|_{\Gamma_*} = \pm N$ then we have

$$N \times (\nabla \times u) = 2N \times (\check{N} \times ((\nabla \check{N})^* u))$$
 on Γ_* .

Find good \tilde{N} defined on $\overline{\Omega'_{\varepsilon}}$ such that

$$\tilde{N}\big|_{\Gamma_0'} = -N$$
 and $\tilde{N}\big|_{\Gamma_1'} = N$.

Define G(u) on the closure of Ω'_{ε} by

$$G(u) = \tilde{N} \times [(\nabla \tilde{N})^* u].$$

Then we have

$$|
abla G(u)| \leq C \varepsilon |
abla u| + C |u| ext{ in } \Omega'_{\varepsilon}.$$

Remark

In the proofs above the role of condition (B) is to obtain $H_0 = \{0\}$.

< ロ > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Remark

In the proofs above the role of condition (B) is to obtain $H_0 = \{0\}$. In fact, we have proved, without using condition (B), the following estimate:

Theorem

Even when Condition (B) is not satisfied, we have

$$\|\tilde{P}\Delta u - \Delta u\|_{L^2(\Omega)} \leq C \|u\|_{H^1(\Omega)},$$

for $u \in H^2(\Omega, \mathbb{R}^3) \cap \tilde{H}$ satisfying the Navier boundary condition on $\partial \Omega$.

Consider the following spherical domains

$$\Omega_{R,R'} = \{ x \in \mathbb{R}^3 : R < |x| < R' \},\$$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

where R' > R > 0.

Consider the following spherical domains

$$\Omega_{R,R'} = \{ x \in \mathbb{R}^3 : R < |x| < R' \},\$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

where R' > R > 0.

Condition (B) is not satisfied and hence $H_0 \neq \{0\}$.

Consider the following spherical domains

$$\Omega_{R,R'} = \{ x \in \mathbb{R}^3 : R < |x| < R' \},\$$

where R' > R > 0.

Condition (B) is not satisfied and hence $H_0 \neq \{0\}$.

Theorem

Let R' > R > 0 and $u \in H^2(\Omega_{R,R'}, \mathbb{R}^3) \cap \tilde{H}$ satisfying the Navier boundary condition on $\partial \Omega_{R,R'}$, then

$$\|\tilde{P}\Delta u - \Delta u\|_{L^2(\Omega_{R,R'})} \leq C\left(\frac{1}{R^2}\|u\|_{L^2(\Omega_{R,R'})} + \frac{1}{R}\|\nabla u\|_{L^2(\Omega_{R,R'})}\right),$$

where C > 0 is independent of R and R'.

Consider the following spherical domains

$$\Omega_{R,R'} = \{ x \in \mathbb{R}^3 : R < |x| < R' \},\$$

where R' > R > 0.

Condition (B) is not satisfied and hence $H_0 \neq \{0\}$.

Theorem

Let R' > R > 0 and $u \in H^2(\Omega_{R,R'}, \mathbb{R}^3) \cap \tilde{H}$ satisfying the Navier boundary condition on $\partial \Omega_{R,R'}$, then

$$\|\tilde{P}\Delta u - \Delta u\|_{L^2(\Omega_{R,R'})} \leq C\left(\frac{1}{R^2}\|u\|_{L^2(\Omega_{R,R'})} + \frac{1}{R}\|\nabla u\|_{L^2(\Omega_{R,R'})}\right),$$

where C > 0 is independent of R and R'.

Proof.

Use $\tilde{N} = e_r$ and do calculations in spherical coordinates.

Consider the following spherical domains

$$\Omega_{R,R'} = \{ x \in \mathbb{R}^3 : R < |x| < R' \},\$$

where R' > R > 0.

Condition (B) is not satisfied and hence $H_0 \neq \{0\}$.

Theorem

Let R' > R > 0 and $u \in H^2(\Omega_{R,R'}, \mathbb{R}^3) \cap \tilde{H}$ satisfying the Navier boundary condition on $\partial \Omega_{R,R'}$, then

$$\|\tilde{P}\Delta u - \Delta u\|_{L^2(\Omega_{R,R'})} \leq C\left(\frac{1}{R^2}\|u\|_{L^2(\Omega_{R,R'})} + \frac{1}{R}\|\nabla u\|_{L^2(\Omega_{R,R'})}\right),$$

くし (1) (

where C > 0 is independent of R and R'.

Proof.

Use $\tilde{N} = e_r$ and do calculations in spherical coordinates.

Remark

In the study of ocean flows: $R' = (1 + \varepsilon)R$.

Consider NSE in Ω'_{ε} with Navier boundary condition.

Consider NSE in Ω'_{ε} with Navier boundary condition. Uniform equivalence of $||Au||_{L^2}$ and $||u||_{H^2}$ when ε is small.

(ロ)、(型)、(E)、(E)、 E) の(の)

Consider NSE in Ω'_{ε} with Navier boundary condition. Uniform equivalence of $||Au||_{L^2}$ and $||u||_{H^2}$ when ε is small. We want

 $C\|u\|_{H^2} \leq \|Au\|_{L^2} \leq \|u\|_{H^2},$

for $u \in D_A$, where *C* is independent of ε . Strategy:

Consider NSE in Ω'_{ε} with Navier boundary condition. Uniform equivalence of $||Au||_{L^2}$ and $||u||_{H^2}$ when ε is small. We want

 $C\|u\|_{H^2} \leq \|Au\|_{L^2} \leq \|u\|_{H^2},$

for $u \in D_A$, where C is independent of ε . Strategy: MISSING: $||u||_{H^2} \le ||\Delta u||_{L^2} + C||u||_{H^1}$.

Consider NSE in Ω'_{ε} with Navier boundary condition. Uniform equivalence of $||Au||_{L^2}$ and $||u||_{H^2}$ when ε is small. We want

 $C\|u\|_{H^2} \leq \|Au\|_{L^2} \leq \|u\|_{H^2},$

for $u \in D_A$, where C is independent of ε . Strategy: MISSING: $||u||_{H^2} \leq ||\Delta u||_{L^2} + C||u||_{H^1}$. Using our result: $||\Delta u||_{L^2} \leq ||Au||_{L^2} + ||Au + \Delta u||_{L^2} \leq ||Au||_{L^2} + C||u||_{H^1}$.

Consider NSE in Ω'_{ε} with Navier boundary condition. Uniform equivalence of $||Au||_{L^2}$ and $||u||_{H^2}$ when ε is small. We want

 $C \|u\|_{H^2} \le \|Au\|_{L^2} \le \|u\|_{H^2},$

for $u \in D_A$, where C is independent of ε . Strategy: MISSING: $||u||_{H^2} \leq ||\Delta u||_{L^2} + C||u||_{H^1}$. Using our result: $||\Delta u||_{L^2} \leq ||Au||_{L^2} + ||Au + \Delta u||_{L^2} \leq ||Au||_{L^2} + C||u||_{H^1}$. MISSING Korn's Inequality: $||u||_{H^1} \leq C||A^{1/2}u||_{L^2} \leq C||Au||_{L^2}$.

Estimate of the Trilinear term $\langle (u \cdot \nabla)u, Au \rangle$.

Estimate of the Trilinear term $\langle (u \cdot \nabla)u, Au \rangle$.

In thin domain, u = v + w where v is 2D-like, and w has good Poincare-like inequalities.
Estimate of the Trilinear term $\langle (u \cdot \nabla)u, Au \rangle$.

In thin domain, u = v + w where v is 2D-like, and w has good Poincare-like inequalities. Then we estimate

$$\begin{aligned} \langle (u \cdot \nabla)u, Au \rangle &= \langle (w \cdot \nabla)u, Au \rangle + \langle (v \cdot \nabla)u, Au \rangle \\ &= \langle (w \cdot \nabla)u, Au \rangle + \langle (v \cdot \nabla)u, Au + \Delta u \rangle \\ &- \langle (v \cdot \nabla)u, \Delta u \rangle. \end{aligned}$$

Estimate of the Trilinear term $\langle (u \cdot \nabla)u, Au \rangle$.

In thin domain, u = v + w where v is 2D-like, and w has good Poincare-like inequalities. Then we estimate

$$\begin{aligned} \langle (u \cdot \nabla)u, Au \rangle &= \langle (w \cdot \nabla)u, Au \rangle + \langle (v \cdot \nabla)u, Au \rangle \\ &= \langle (w \cdot \nabla)u, Au \rangle + \langle (v \cdot \nabla)u, Au + \Delta u \rangle \\ &- \langle (v \cdot \nabla)u, \Delta u \rangle. \end{aligned}$$

One of the above terms

$$\begin{aligned} |\langle (\mathbf{v} \cdot \nabla) u, Au + \Delta u \rangle| &\leq C \|\mathbf{v} | \nabla u \|_{L^{2}} (\varepsilon \|u\|_{H^{1}} + \|u\|_{L^{2}}) \\ &\leq C \{ \varepsilon^{-1/4} \|u\|_{L^{2}}^{1/2} \|u\|_{H^{1}} \|u\|_{H^{2}}^{1/2} + \|u\|_{L^{2}}^{1/2} \|u\|_{H^{1}}^{1/2} \|u\|_{H^{2}}^{1/2} \\ &\times (\varepsilon \|u\|_{H^{1}} + \|u\|_{L^{2}}). \end{aligned}$$

which is acceptable.

Other discussions

- Non-linear estimate
- Commutator estimate
- Other boundary conditions.

(ロ)、(型)、(E)、(E)、 E) の(の)

In the Key Lemma, what do we get if Φ is $(u \cdot \nabla)u$ or related term? Can we use this to improve the estimate of the trilinear term?

(ロ)、(型)、(E)、(E)、 E) の(の)

Liu-Pego proved for Dirichlet boundary condition in general $\boldsymbol{\Omega}$ that

・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・
・

$$\|P\Delta u - \Delta Pu\|_{L^2} \leq (\varepsilon + \frac{1}{2})\|u\|_{H^2} + C_{\varepsilon}\|u\|_{H^1}.$$

for $u \in H^2 \cap H_0^1$.

Example: friction boundary condition on $\partial \Omega$:

$$u \cdot N = 0$$
, $[(Du)N]_{tan} + \alpha u = 0$,

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

where $\alpha > 0$ is the friction coefficient.

Example: friction boundary condition on $\partial \Omega$:

$$u \cdot N = 0$$
, $[(Du)N]_{tan} + \alpha u = 0$,

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

where $\alpha > 0$ is the friction coefficient. In thin domain Ω_{ε} , the friction $\alpha = \alpha_{\varepsilon}$.

Example: friction boundary condition on $\partial \Omega$:

$$u \cdot N = 0$$
, $[(Du)N]_{tan} + \alpha u = 0$,

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

where $\alpha > 0$ is the friction coefficient. In thin domain Ω_{ε} , the friction $\alpha = \alpha_{\varepsilon}$. If $\alpha_{\varepsilon} = O(\varepsilon)$ as $\varepsilon \to 0$, the same method works.

Example: friction boundary condition on $\partial \Omega$:

$$u \cdot N = 0$$
, $[(Du)N]_{tan} + \alpha u = 0$,

where $\alpha > 0$ is the friction coefficient. In thin domain Ω_{ε} , the friction $\alpha = \alpha_{\varepsilon}$. If $\alpha_{\varepsilon} = O(\varepsilon)$ as $\varepsilon \to 0$, the same method works. What if $\alpha_{\varepsilon} \leq \alpha$? (more...in Spring or next Fall!)

THANK YOU FOR YOUR TIME AND ATTENTION. (this is my first presentation with BEAMER)

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Miscellaneous

Green's formula: for $u \in H^2(\Omega_{\varepsilon})$ and $v \in H^1(\Omega_{\varepsilon})$:

$$\int_{\Omega_{\varepsilon}} \Delta u \cdot v dx = \int_{\Omega_{\varepsilon}} -2(Du:Dv) + (\nabla \cdot u)(\nabla \cdot v) dx$$
$$+ \int_{\partial \Omega_{\varepsilon}} \{2((Du)N) \cdot v - (\nabla \cdot u)(v \cdot N)\} d\sigma.$$

◆□▶ ◆□▶ ◆∃▶ ◆∃▶ = のへで